



Rao Bahadur Y Mahabaleswarappa Engineering College (RYMEC)
(Formerly , Vijayanagara Engineering College (VEC), Ballari)



Welcome to RYMEC Family.



Rao Badhur Y Mahabaleshwarappa Engineering College (RYMEC), BALLARI.



Dr. CHITRIKI THOTAPPA (MECH – 1987-1991)

PROFESSOR & M.Tech Co-Ordinator, Dept. of Mech.

SECRETARY - RYMEC, Alumni Association

QUALIFICATION:

BE (Mech) 1991 - (Gulbarga University)

ME (PM) 1994 - (Karnataka University)

Ph.D (SCM) 2012 - (Sree Venkateshwara University)

EXPERIENCE : 26 yrs Teaching, 1 yr Industry, 8 yrs Research.

PRESENTATION

on

ENGINEERING GRAPHICS (EG) : (18EGDL15/25)

ENGINEERING GRAPHICS

Semester	: I/II	CIE Marks	: 40
Course Code	: 18EGDL15/25	SEE Marks	: 60
Teaching Hours/week (L:T:P)	: 2:0:2	Exam Hours	: 03
Credits : 03			

Course Learning Objectives:

This course will enable students to

- CLO1** To expose the students to standards and conventions followed in preparation of engineering drawings.
- CLO2** To make them understand the concepts of orthographic and isometric projections.
- CLO3** Develop the ability of conveying the engineering information through drawings.
- CLO4** To make them understand the relevance of engineering drawing to different engineering domains.
- CLO5** To develop the ability of producing engineering drawings using drawing instruments.
- CLO6** To enable them to use computer aided drafting packages for the generation of drawings.

Question paper pattern:

- Module -1 is only for practice and CIE and not for examination.
- Question paper for each batch of students will be sent online by VTU and has to be downloaded before the commencement of Examination of each batch. The answer sheets will have to be jointly evaluated by the Internal & External examiners.
- A maximum of THREE questions will be set as per the following pattern (No mixing of questions from different Modules).

Textbooks:

1. **Engineering Drawing** – N.D. Bhatt & V.M. Panchal, 48th edition, 2005-Charotar Publishing House, Gujarat.
2. **Engineering Graphics** – K.R. Gopalakrishna, 32nd edition, 2005-Subash Publishers Bangalore.
3. **Computer Aided Engineering Drawing** - by Dr. M H Annaiah, Dr C N Chandrappa and Dr. B Sudheer Premkumar, Fifth edition, New Age International Publishers.

Reference Books:

1. **Computer Aided Engineering Drawing** – S. Trymbaka Murthy, – I.K. International Publishing House Pvt. Ltd., New Delhi, 3rd revised edition-2006.
2. **Engineering Drawing**-by N.S.Parthasarathy & Vela Murali, Oxford University Press, 2015
3. **Fundamentals of Engineering Drawing with an Introduction to Interactive Computer Graphics for Design and Production**- Luzadder Warren J., Duff John M., Eastern Economy Edition, 2005- Prentice-Hall of India Pvt. Ltd., New Delhi.
4. **A Primer on Computer Aided Engineering Drawing-2006**, Published by VTU, Belgaum.

MODULE-I

Introduction to Computer Aided Sketching:

Introduction, Drawing Instruments and their uses, relevant BIS conventions and standards. Lettering, line conventions, dimensioning, material conventions, and free hand practicing.

Computer screen, layout of the software, standard tool bar / menu and description of most commonly used tool bars, and navigational tools.

Co-ordinate system and reference planes HP, VP, RPP & LPP of 2D/3D environment. Selection of drawing sheet size and scale.

Commands and creation of Lines, coordinate points, axes, poly-lines, square, rectangle, polygons, splines, circles, ellipse, text, move, copy, off-set, mirror, rotate, trim, extend, break, chamfer, fillet, curves, constraints viz., tangency, parallelism, inclination and perpendicularity.

MODULE-II

Orthographic projections of points, straight lines and planes:

Introduction, Definitions - Planes of projection, reference line and conventions employed. First angle and Third angle projection.

Projections of straight lines (located in first quadrant/first angle only), true and apparent lengths, true and apparent inclinations to reference planes (No application problems and midpoint problems).

Orthographic projections of plane surfaces (First angle projection only):

Projections of regular plane surfaces—triangle, square, rectangle, pentagon, hexagon and circle—in simple positions inclined to both the planes; planes in different positions by change of position method only. (No problems on punched plates and composite plates).

MODULE – III

Projections of solids:

Introduction, definitions – projections of right regular tetrahedron, hexahedron (cube), prisms, pyramids, and cones with axis inclined to both the planes. (Solids resting on HP only and no problems on octahedrons, and freely suspended solids.)

MODULE IV

Development of Lateral Surfaces of Solids:

Introduction to section planes and sectional views.

Development of lateral surfaces of right regular prisms, cylinders, pyramids, and cones resting with base on HP only. Development of their frustums and truncations. (No problems on lateral surfaces of trays, tetrahedrons, spheres and transition pieces).

MODULE-V

Isometric Projection (using isometric scale only)

Introduction, Isometric scale, Isometric projection of simple plane figures, Isometric projection of hexahedron(cube), right regular prisms, pyramids, cylinders, cones, and spheres. Isometric projection of combination of two simple solids. Conversion of given isometric/ pictorial views to orthographic views of simple objects.

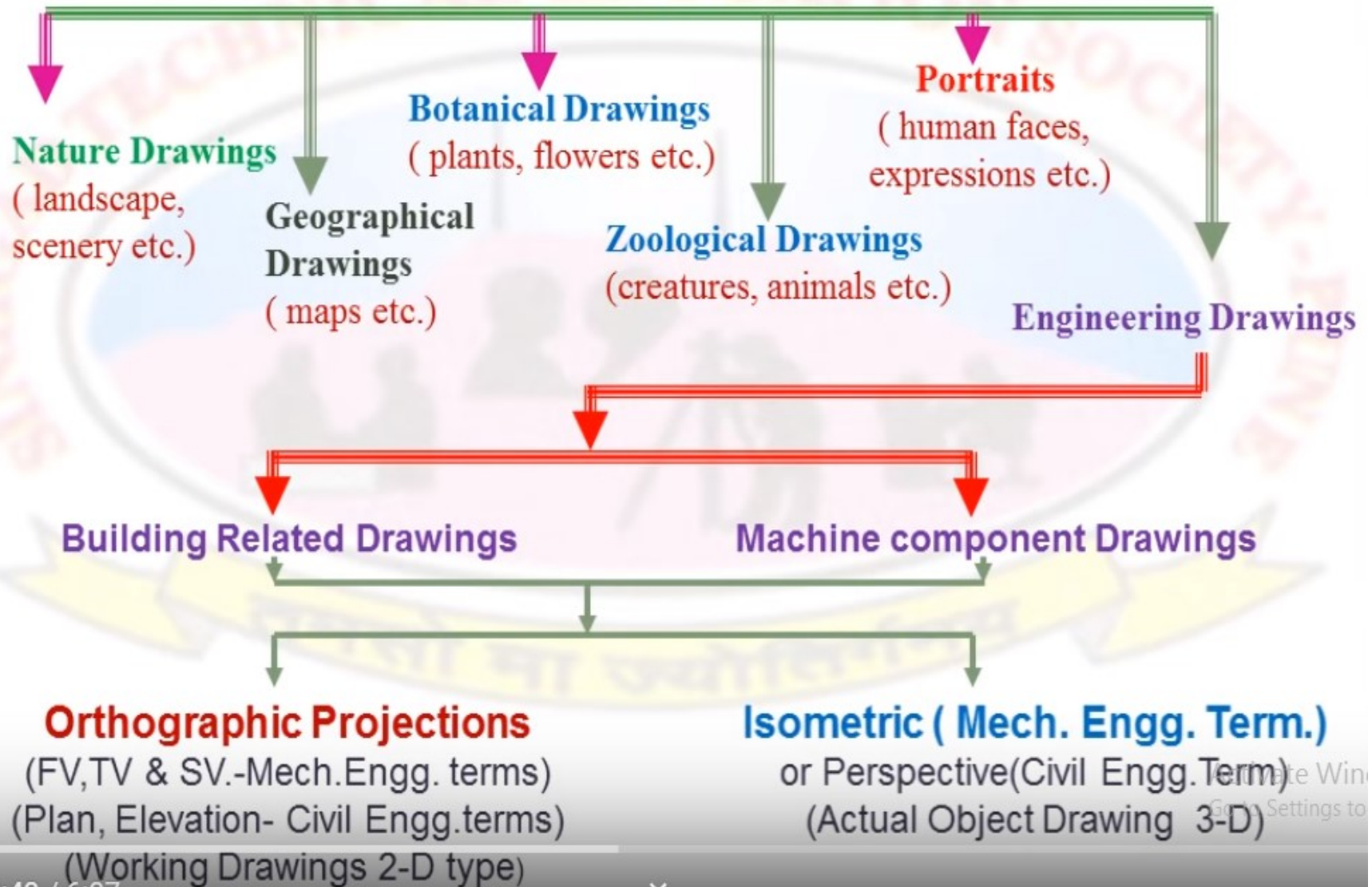
LIST OF ENGINEERING DRAWING MATERIALS

Following **Engineering Graphic materials** required for the class work.

(All **materials** should be of **good quality**).

1. 200 pages un-ruled long note book.
2. Soft rubber/Eraser .
3. 2 No. Micro tip pencil 1 No. HB and 1 No. 2H .
4. Compass.
5. Protractor.
6. Long plastic scale.
7. Sketch book.
8. Engineering Drawing question bank with solutions by VTU.

Types of Drawings



MODULE – II (ORTHOGRAPHIC PROJECTION)

INTRODUCTION:

- To **manufacture the Product/Object** it is necessary to have its (Object) drawing in its true shape and true size.
- **2-Dimensional** objects like **Planes** (**Triangle, Square, Rectangle, Pentagon, Hexagon, Circle etc.**) Their true shape and true size drawings on a 2 – Dimensional drawing sheet **can be drawn very easily.**
- **3 – Dimensional** objects like **Solids** (**Cube, Prisms, Pyramids, Cylinders, Cone, Sphere etc.**) Their drawing in true shape and true size **cannot be drawn easily** on a 2 – Dimensional drawing sheet.

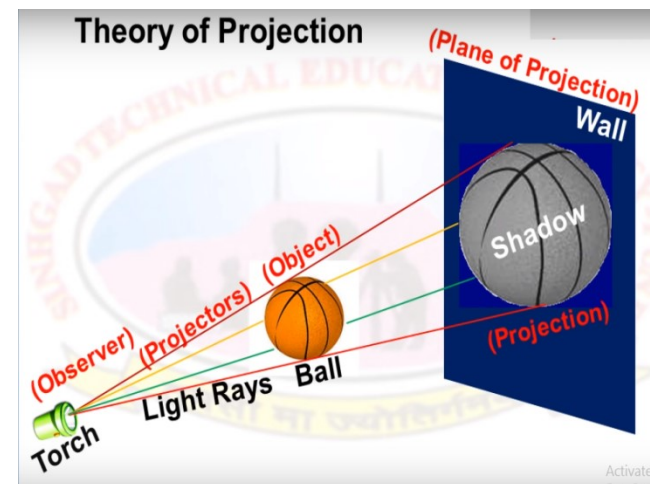
- However, **Solid objects** which are **3-Dimension** can be drawn in 3-Dimensional drawing/view (Isometric View) on a drawing sheet (2-Dimensional), But its shape and size will not be true.
- **3-Dimensional drawing** will **only give the idea of object shape**, So these drawings cannot be effectively used for Object/Product manufacturing.
- Therefore, to **obtain true shape and true size drawings** of 3-Dimensional (Solids) objects it is **necessary to use Principles of Orthographic projection**.
-

PRINCIPLES OF PROJECTION.

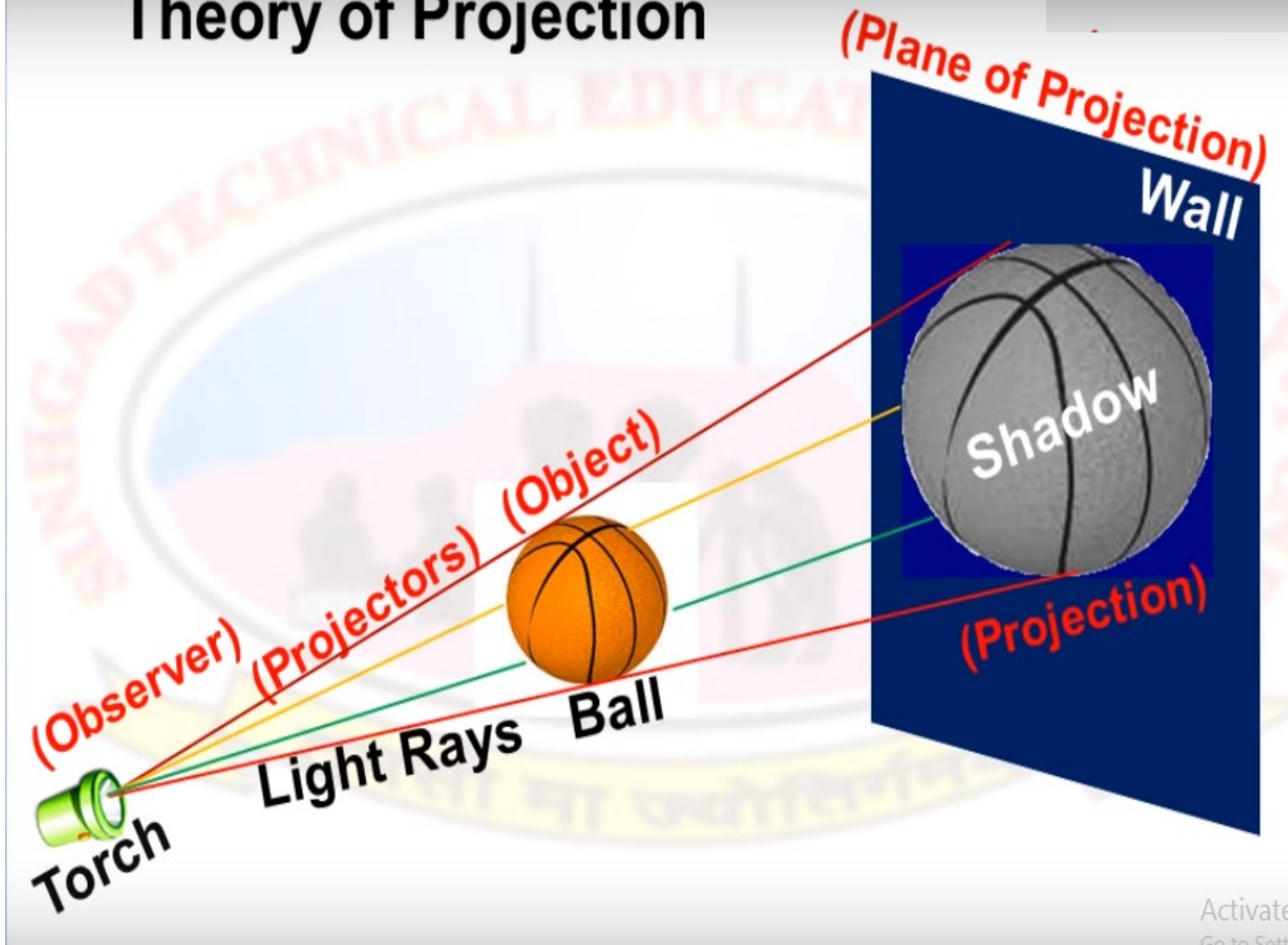
- The word **PROJECTION** is a Latin word means to **throw forward**.
- In **Engineering drawing Projection** means **throwing forward the image / View of an object on to a Screen.**
- **PROJECTOR** is a device which projects the image of an object on to a **Screen/Wall.**

To obtain the **Image / View of an object** the following **3 things** are required.

1. **Light source / Observer**
2. **Object**
3. **Screen (Wall) / Plane of Projection**
(Reference Plane)



Theory of Projection



Projection means “To throw Forward”.

In this Object are being thrown (projected) forward in the form of Projection/Image/View

Torch → Ball → Shadow → Wall

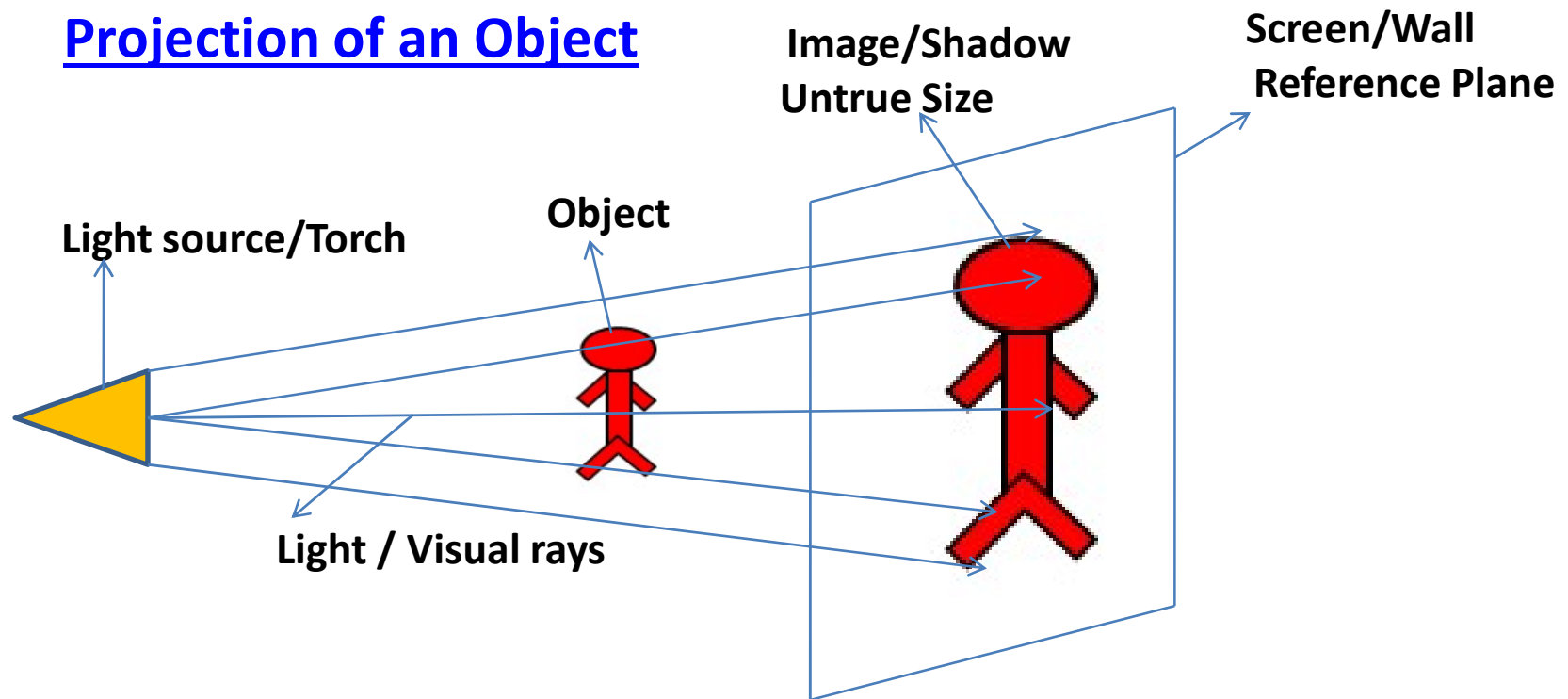
Light Source/Torch → Observer

Ball → Object

Shadow → Projection/ View/Image

Wall → Plane of Projection (POP)
/Reference Planes/Screen

Projection of an Object

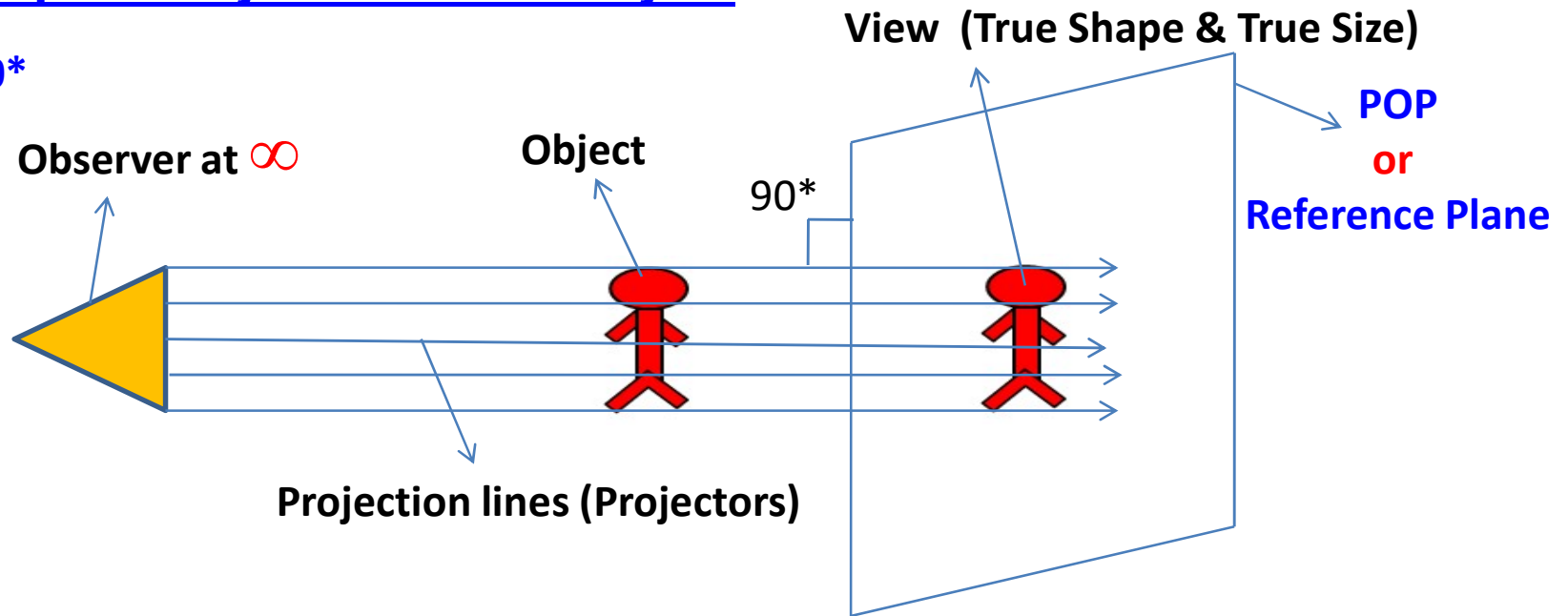


Note:

- **Observer/Light source** is at **definite place**.
- **Light rays / Projections lines** are **diverging** and **Inclined to POP**.
- **Image / View** is always **true shape**, but **un-true size**, as the position of the POP, Object & Observer changes Image / View size also changes.

Orthographic Projection of an Object

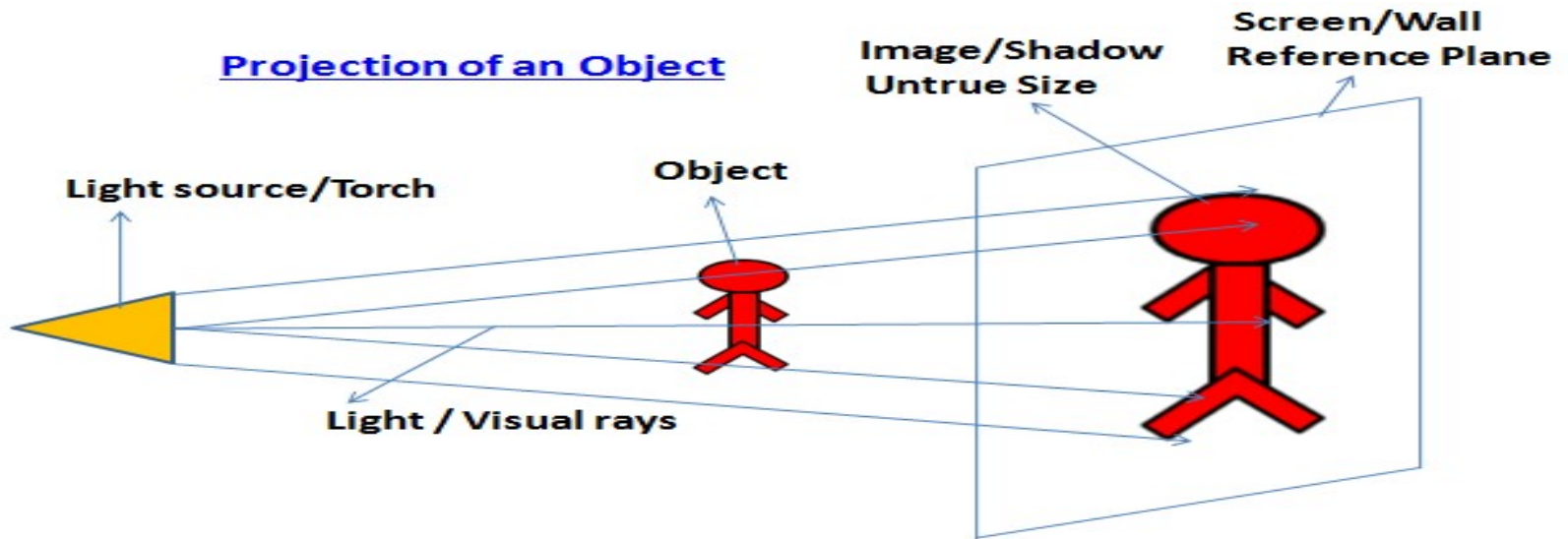
Ortho – 90*



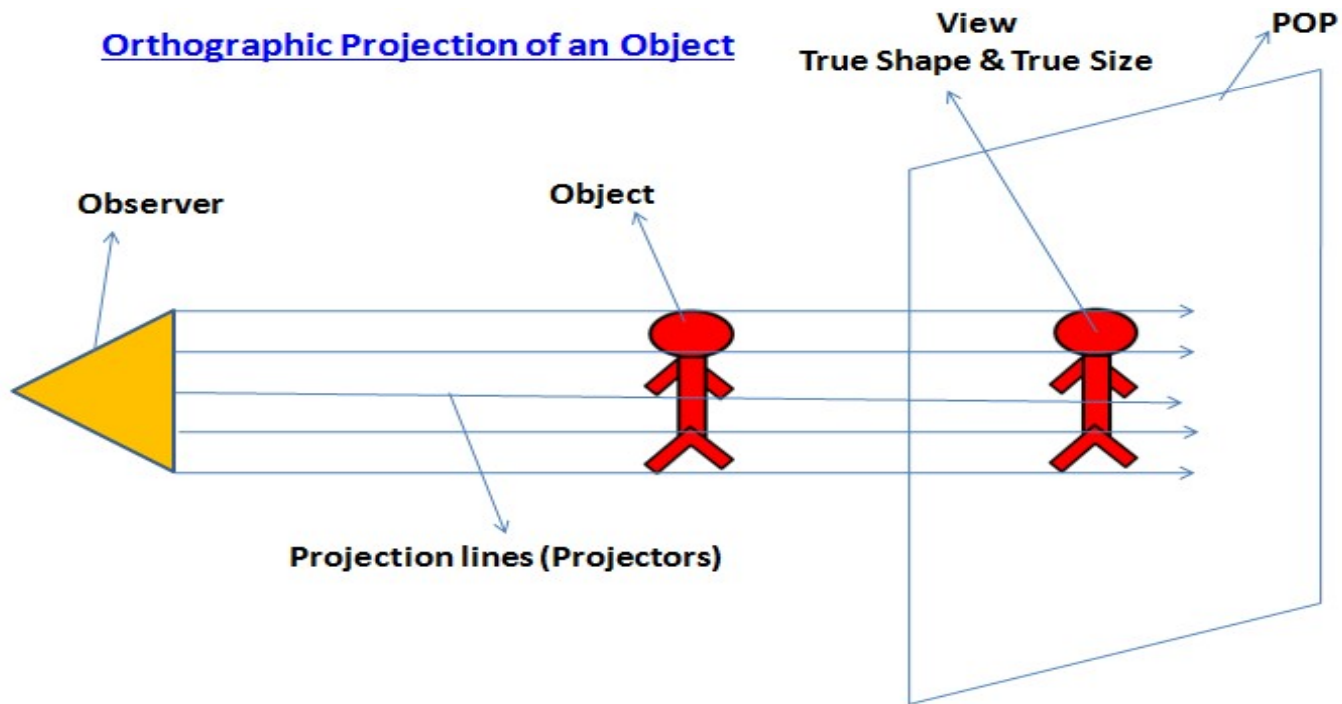
Note: POP – Plane Of Projection

- Observer is at **Infinity** ∞.
- Projections lines are **parallel to each other** and **Perpendicular/Normal/90*** to POP.
- View is always **true shape** and **true size**, irrespective of the position of the POP, Object & Observer (i.e., Size and Shape of the View will not change).

Projection of an Object

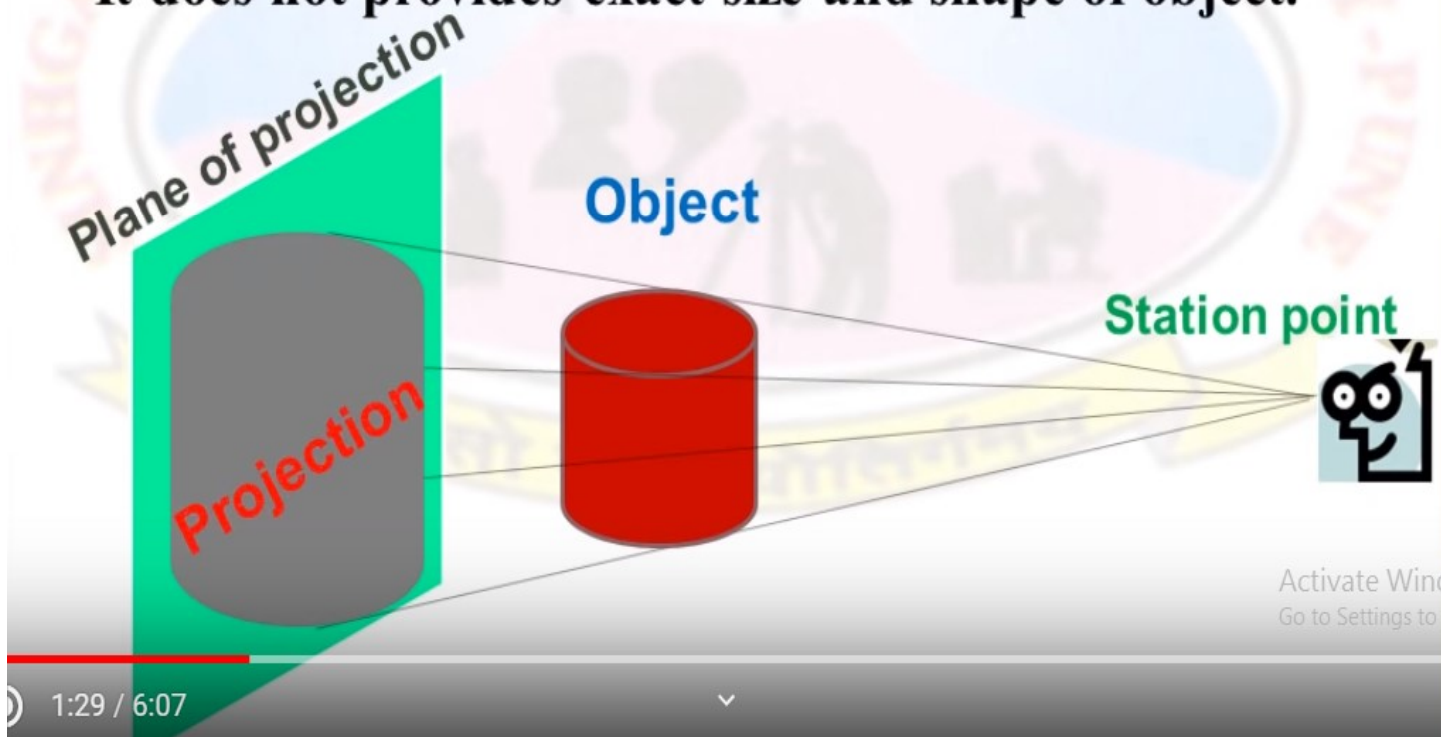


Orthographic Projection of an Object



Perspective Projection

- * **Observer** is at **finite distance**.
- * **Rays or Projectors** are **converging** at observer's eye.
- * It does not provides exact size and shape of object.



Orthographic Projection

Latin
Origin

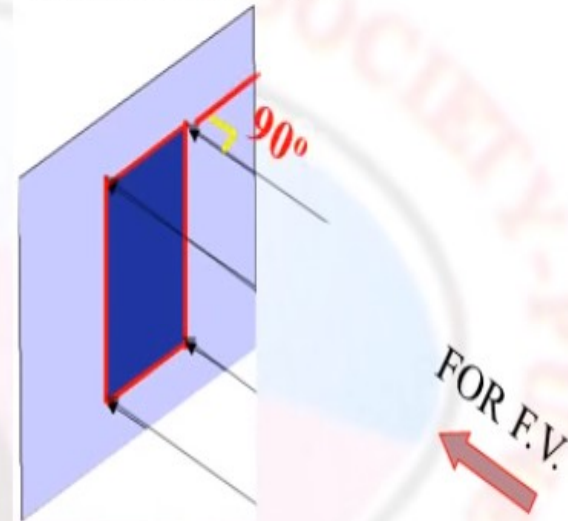
- * **ORTHO** means **Perpendicular**.
- * Assume that **observer** is at **infinite distance** and rays or **Projection** lines are **Parallel to each other** and **Perpendicular** to the **Plane of Projection**.
- * Since the projectors are perpendicular to the plane of projection, the view is called **Orthographic View** and the projection method is called **Orthographic projection**.

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Orthographic Projection

* Orthographic projection is a two dimensional projection method.

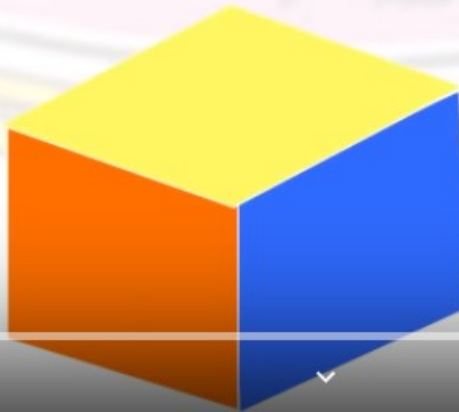
* FV : Length and height of Object



* As projectors are Parallel to each other, the size of Orthographic View of an object is equal to the actual size of an object.

Isometric Projection

- * **Observer** is at **infinite distance**.
- * **Rays or Projectors** are **parallel** to each other & **perpendicular** to the **plane of projection**.
- * **All faces of the object** are **equally inclined to the planes of projection**.
- * **All faces of the object** are **visible in a single view**.



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PRINCIPAL VIEWS & PRINCIPAL PLANES OF PROJECTION (POP)

PRINCIPAL VIEWS

Complete details of the object like all the **sizes** and **shape** of the object cannot be obtained in a single view, they are obtained in more than one view of an object.

For any Object **Max. of 6 views** can be obtained/drawn they are:

- **Front View (FV), Top View (TV), Right Side View (RSV), Left Side View (LSV), Rear View (RV)** and **Bottom View (BV)**.

But, all views of the object may not be required to know the complete details of the object.

- **Simple shape object** may require only **2 views** and
- **complex shape objects** may require **3-4 Views**.

PRINCIPAL VIEWS & PRINCIPAL PLANES OF PROJECTION (POP)

4- Principal Views of an Object are :

1. **Front View (FV)**
2. **Top View (TV)**
3. **Right Side/Profile View (RSV / RPV) &**
4. **Left Side/Profile View (LSV / LPV).**

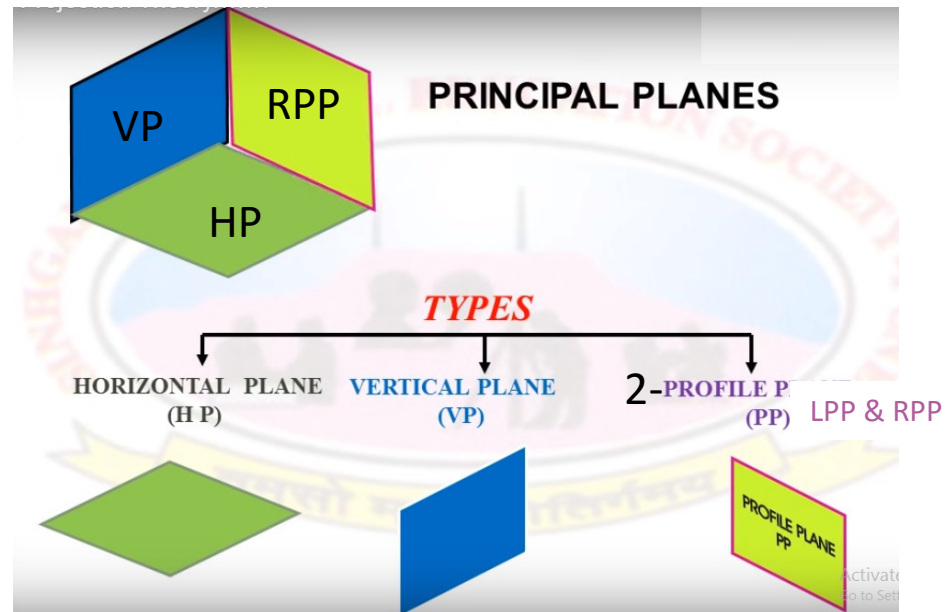
PRINCIPAL VIEWS & PRINCIPAL PLANES OF PROJECTION (POP)

PRINCIPAL PLANES OF PROJECTION (POP):

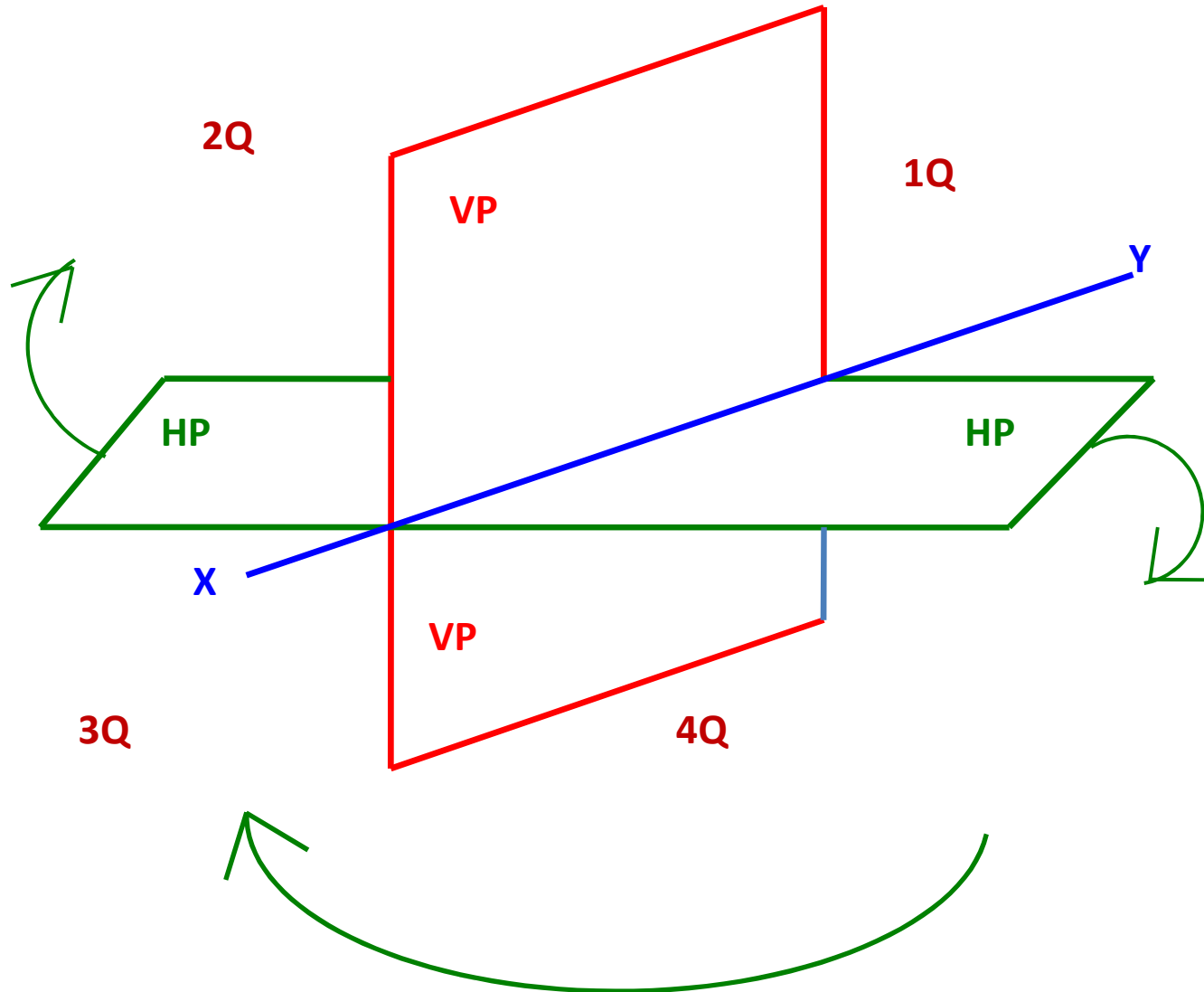
These are also called **reference planes**, where views of the object are drawn/obtained.

Four (4) Principal Planes of Projections : 4 Principal views are obtained on 4 Principal Planes of Projections (POP) they are:

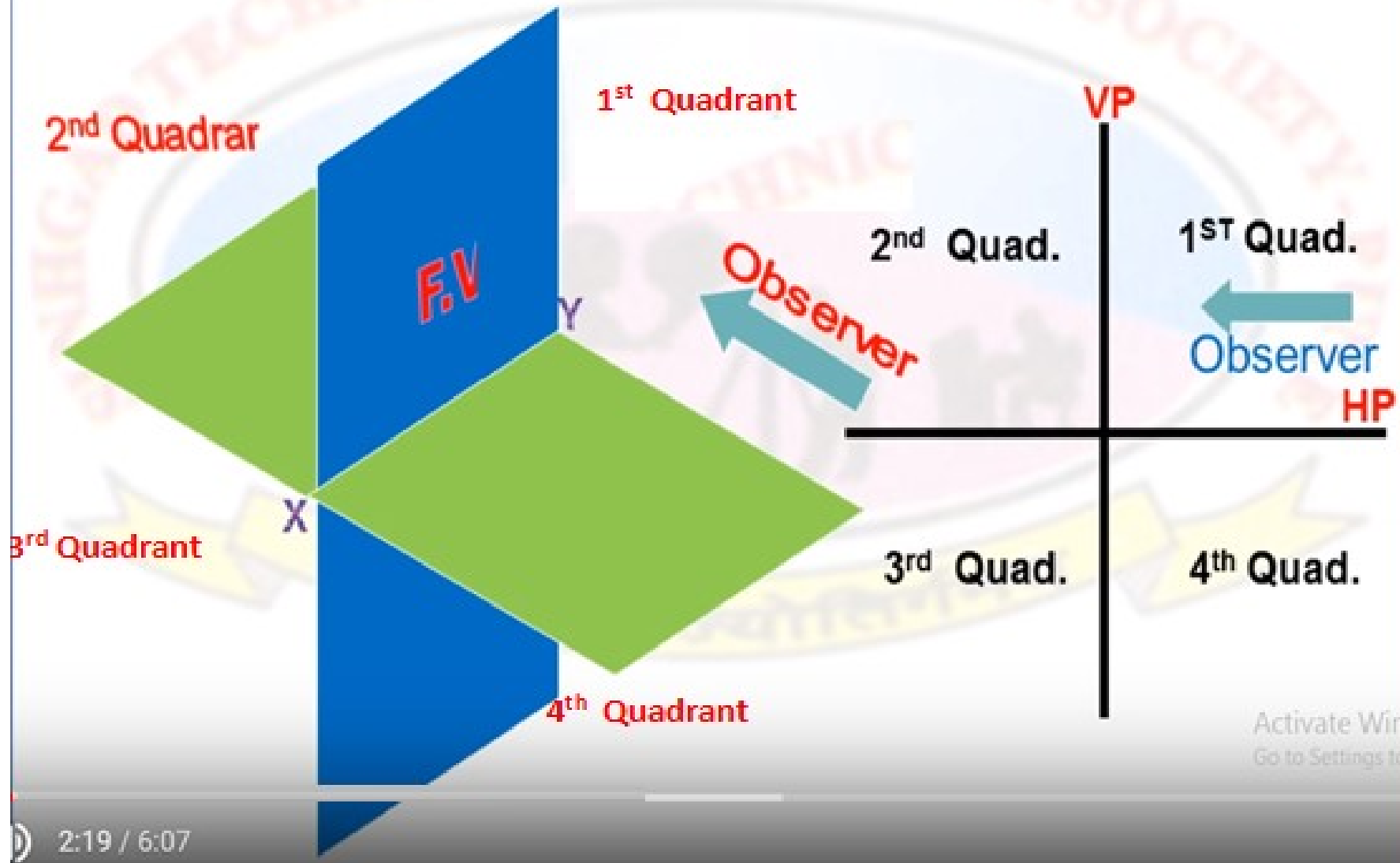
1. **Horizontal Plane (HP)**
2. **Vertical Plane (VP)**
3. **Right Side/Profile Plane (RPP)**
4. **Left Side/Profile Plane (LPP)**



4 – Quadrant System

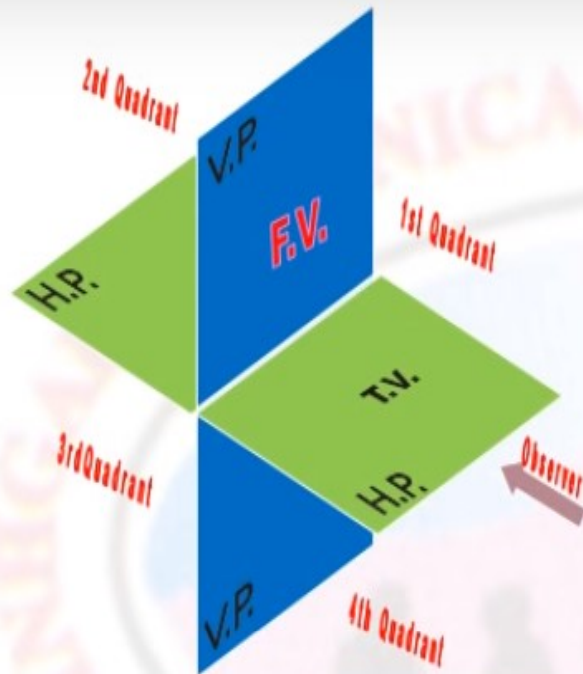


Quadrant system



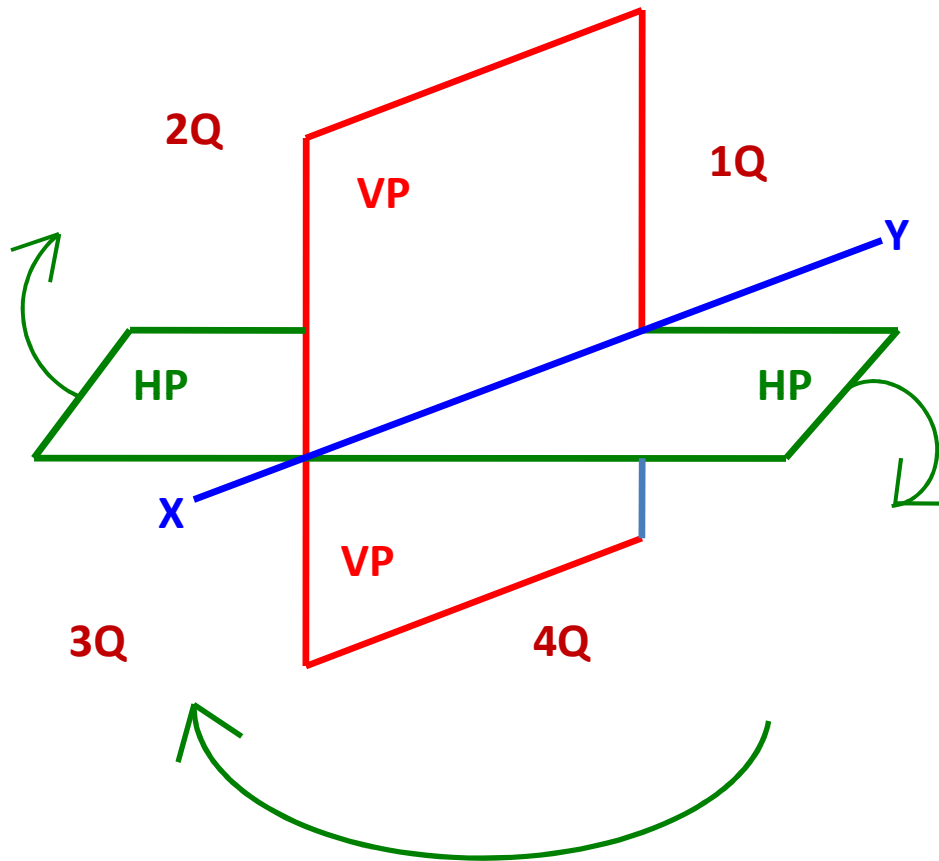
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Quadrant system



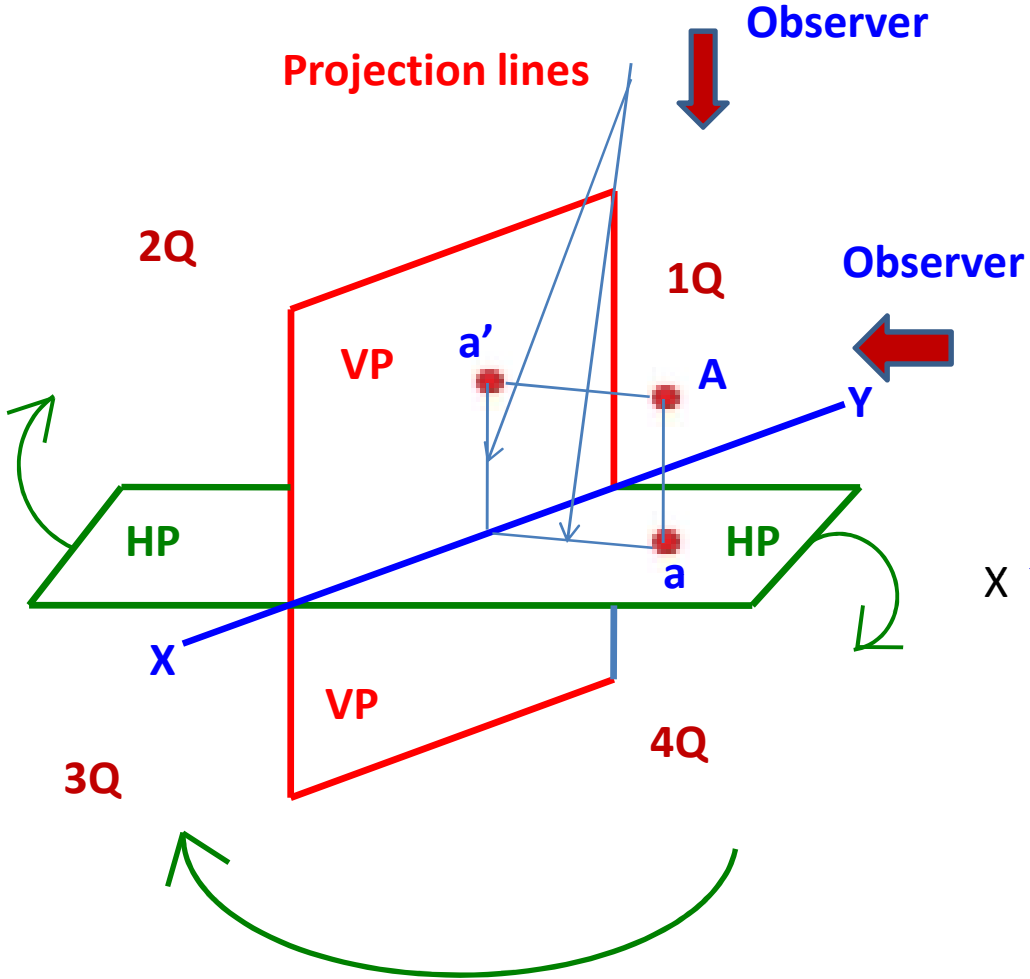
Quadrant	Observer; Object; Plane positions	Position of object w.r.t. planes of projection
First	Observer – Object – Plane	Above HP, In Front of VP
Second	Observer – Plane – Object	Above HP, Behind VP
Third	Observer – Plane – Object	Below HP, Behind VP
Fourth	Observer – Object – Plane	Below HP, In Front of VP

4 – Quadrant System

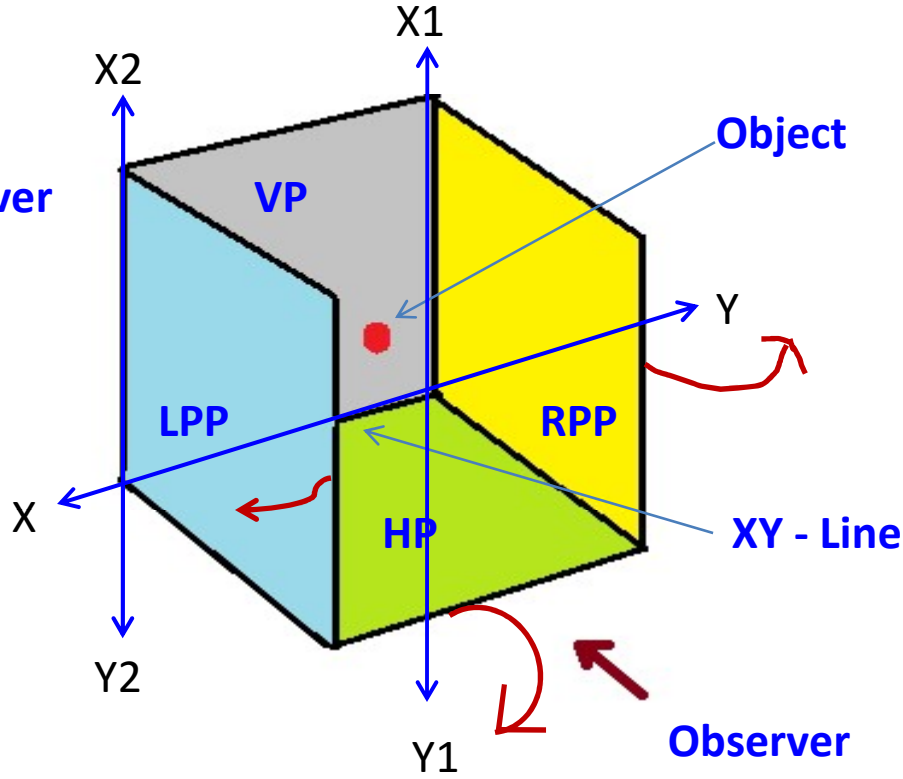


- **4-Quadrant system** is formed in the space when the **Horizontal plane (HP)** and **Vertical Plane (VP)** bisect each other or assumed to extend beyond the **line of intersection (XY)**.
- Intersection of VP & HP is called **Line of intersection (XY line)** or **Reference line**.
- POP's are **perpendicular** to each other and they are **transparent** in nature.

4 – Quadrant System

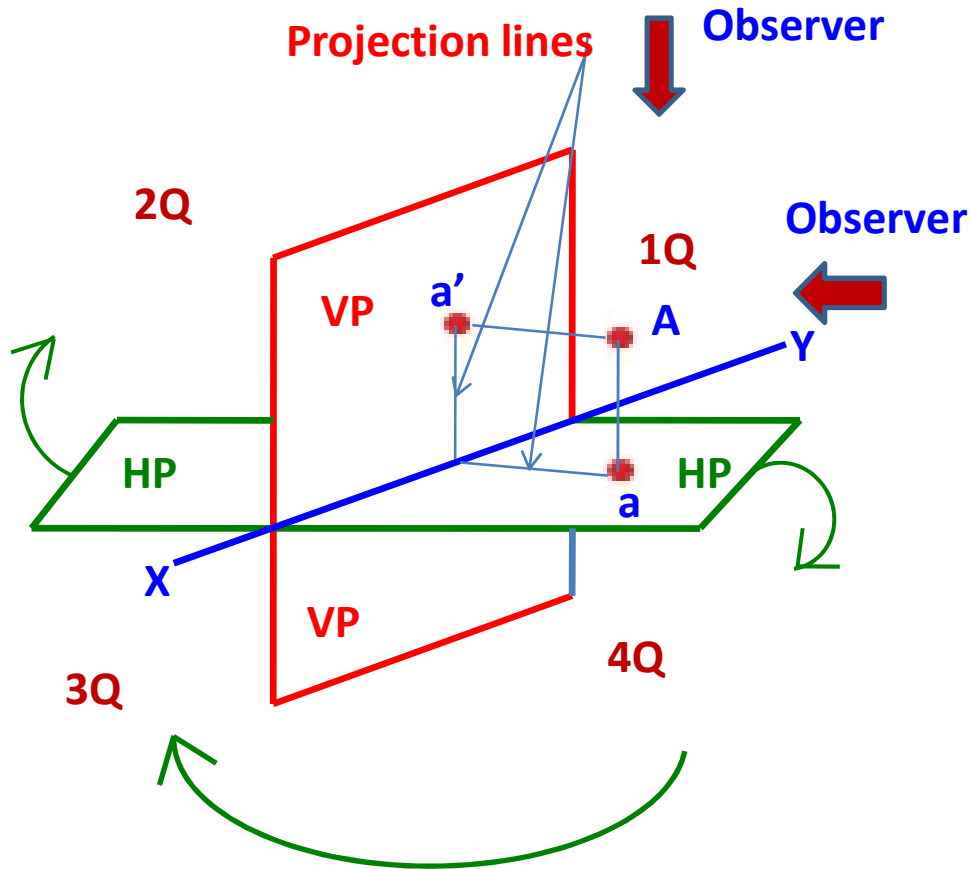


1 - Quadrant



DIFFERENT ANGLES OF ORTHOGRAPHIC PROJECTION

(Based on the object location with reference to Quadrant)



4 – Quadrant System

Depending upon the **position** or **location** of the **object** in different quadrants, there are four angles of Projection.

- **1st Angle Projection.**
- **2nd Angle Projection.**
- **3rd Angle Projection.**
- **4th Angle Projection.**

First Angle Projection: If the Object is in the **1st Quadrant** and views are taken, then it is called as First Angle Projection

DIFFERENT ANGLES OF ORTHOGRAPHIC PROJECTION
(Based on the object location with reference to Quadrant)

- **First Angle Projection:** If the Object is in the **1st Quadrant** and views are taken, then it is called as First Angle Projection.

- **Second Angle Projection:** : If the Object is in the **2nd Quadrant** and views are taken, then it is called as Second Angle Projection.

- **Third Angle Projection:** If the Object is in the **3rd Quadrant** and views are taken, then it is called as Third Angle Projection.

- **Fourth Angle Projection:** : If the Object is in the **4th Quadrant** and views are taken, then it is called as Fourth Angle Projection.

DIFFERENT ANGLES OF ORTHOGRAPHIC PROJECTION
(Based on object location with reference to POP's (HP&VP))

NOTE:

- Assuming that POP's transparent, POP's Perpendicular/Normal to each other.
- Position of the observer will not change, irrespective of the object located in any Quadrant.

- **First Angle Projection (In 1Q)** : Object will be **Above HP / On HP** and **In-front of VP/On VP.**

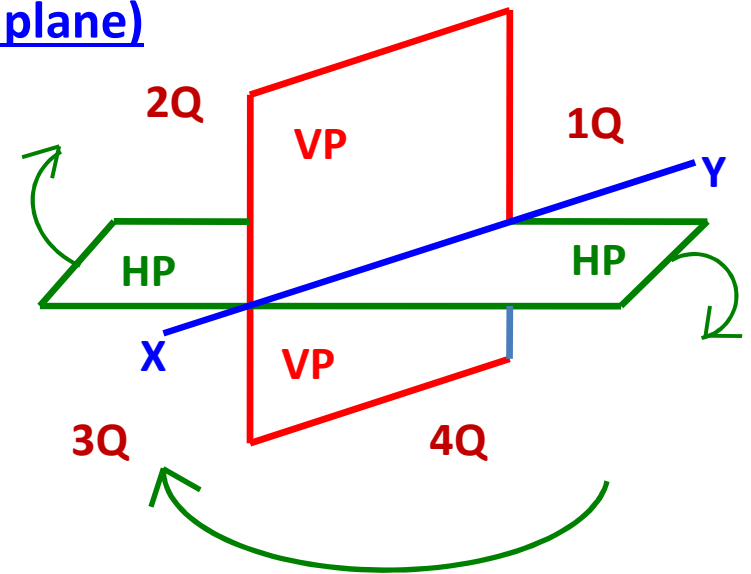
- **Second Angle Projection (In 2Q)** : Object will be **Above HP/ On HP** and **Behind VP/On VP.**

- **Third Angle Projection (In 3Q)** : Object will be **Below HP/ On HP** and **Behind VP/On VP.**

- **Fourth Angle Projection(In 4Q)** : Object will be **Below HP / On HP** and **In-front of VP/On VP.**

ROTATION OF PLANES OF PROJECTIONS (POP'S)

(To get all POP's on a single plane)

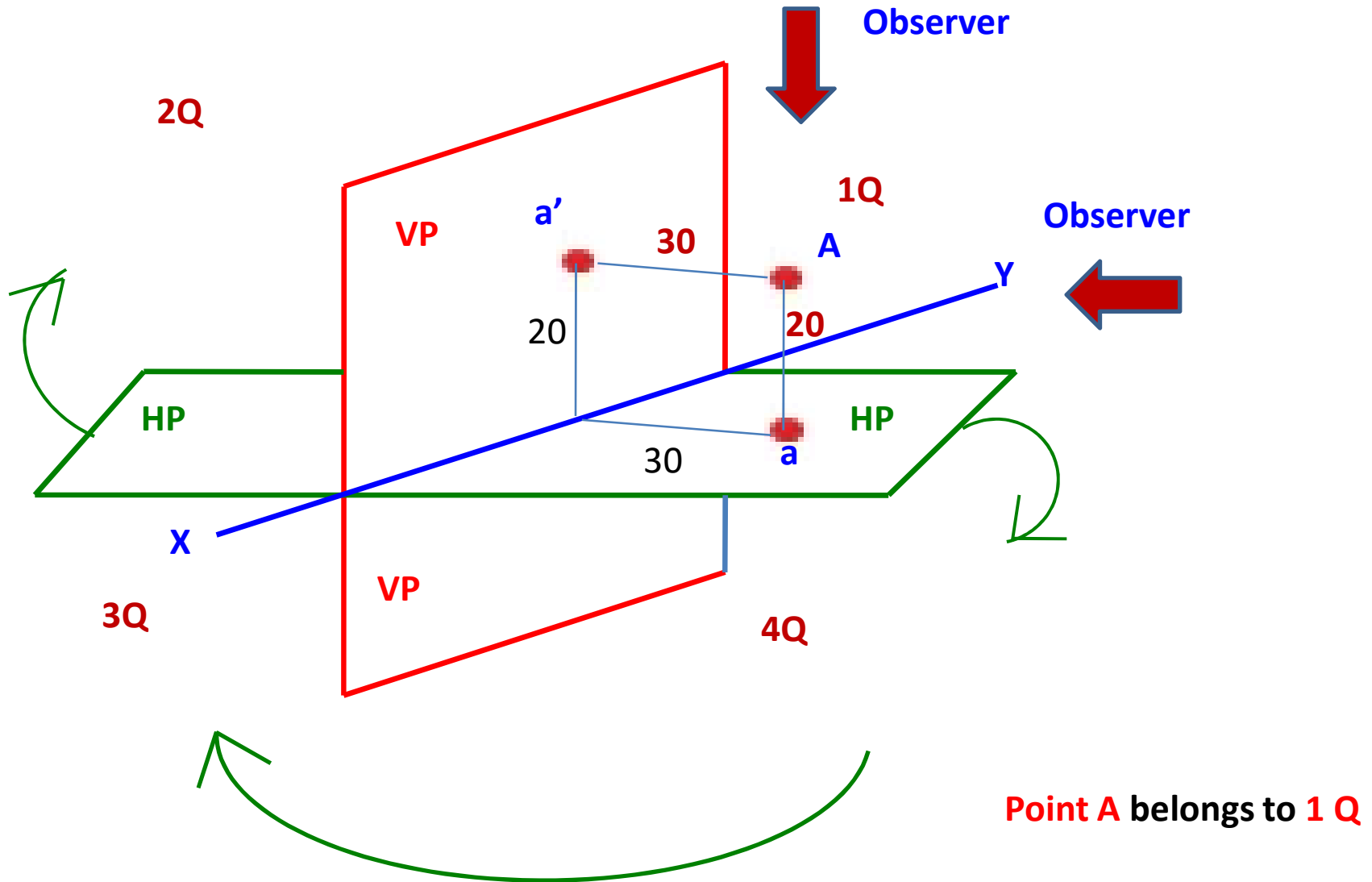


In order to obtain all POP's on a single plane:

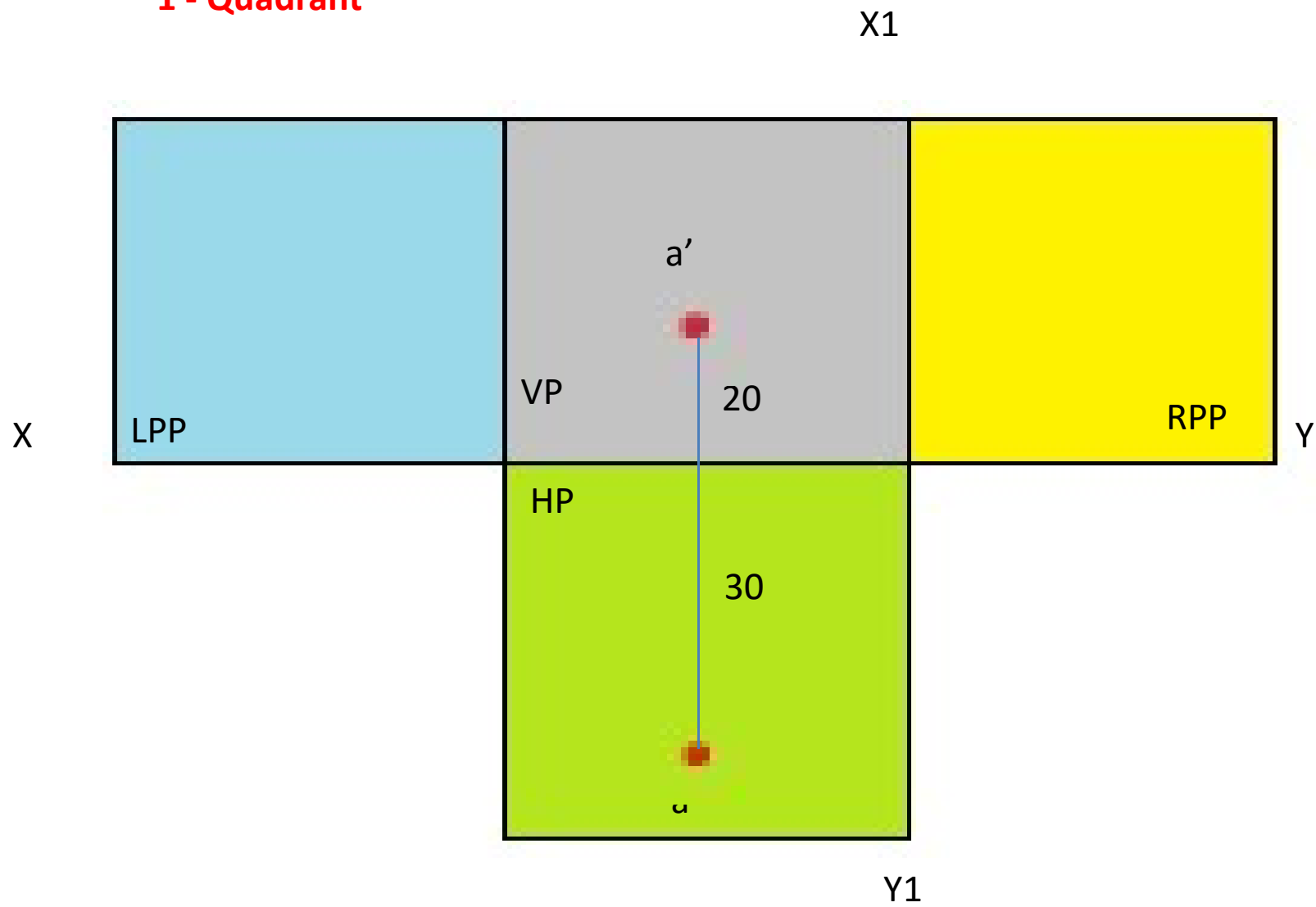
- **Vertical Plane (VP)** - Always kept stationary.
- **Horizontal planes (HP)** - Are rotated about line of intersection (i.e. XY line) through 90° in **Clockwise direction**.
- **Side/Profile planes (RPP & LPP)** - Are rotated against VP through 90° about line of intersection (X1 Y1 & X2 Y2).

So that all POP's comes on a single plane.

Point (Object) A is **20 mm above HP** and **30 in-front of VP**, Draw the Projections of point A (i.e. Draw its FV & TV) and state in which Quadrant it Belongs to.



1 - Quadrant



NOTE:

- All above / Below **HP dimensions** are seen in **VP**.
- All in-front / Behind **VP dimensions** are seen in **HP**.
- Always **RPP & LPP** are attached to **VP** (Right side to VP is RPP & left side to VP is LPP)

NOTE:

1. If **Point B** lies on **HP**, then its front view (FV=**b'**) **lies on XY line**.
2. If **Point B** lies on **VP**, then its (TV = **b**) **lies on XY line**.
3. If **Point C** lies on both **HP and VP**, then both (FV & TV) i.e., **c'** & **c** lies on XY line. Then the location of Point C may be considered in any Quadrant, but consider it in a 1st Q.

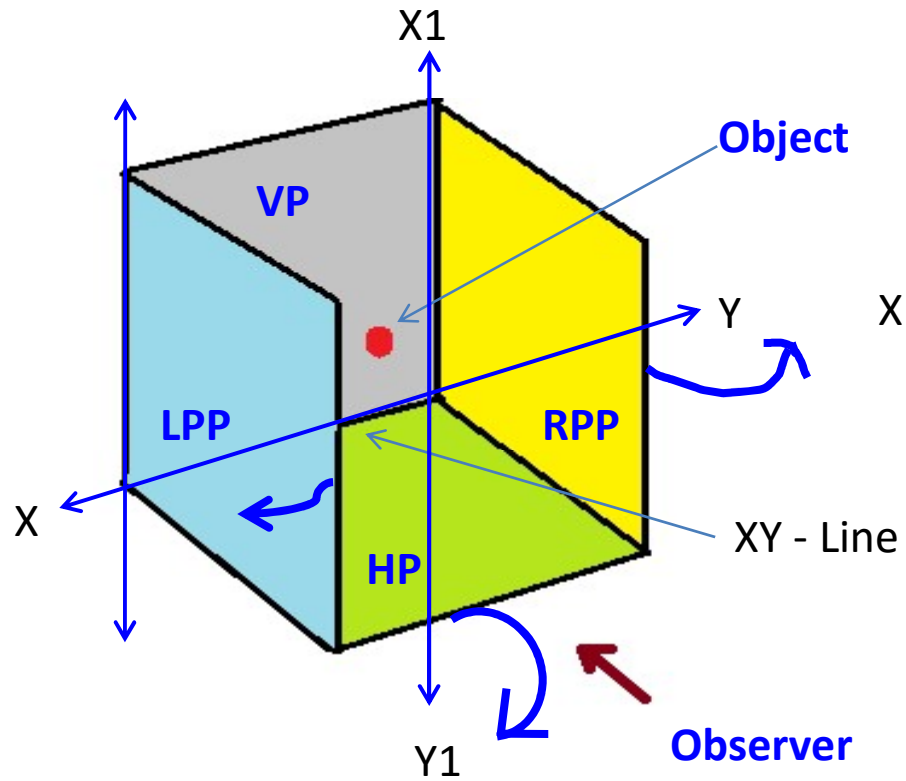
STANDARD NOTATION / REPRESENTATION OF VIEWS

To avoid confusion and to have uniformity always **Views** are represented by **lower/small case letters** only and **Object** is named / represented by **Capital letters**.

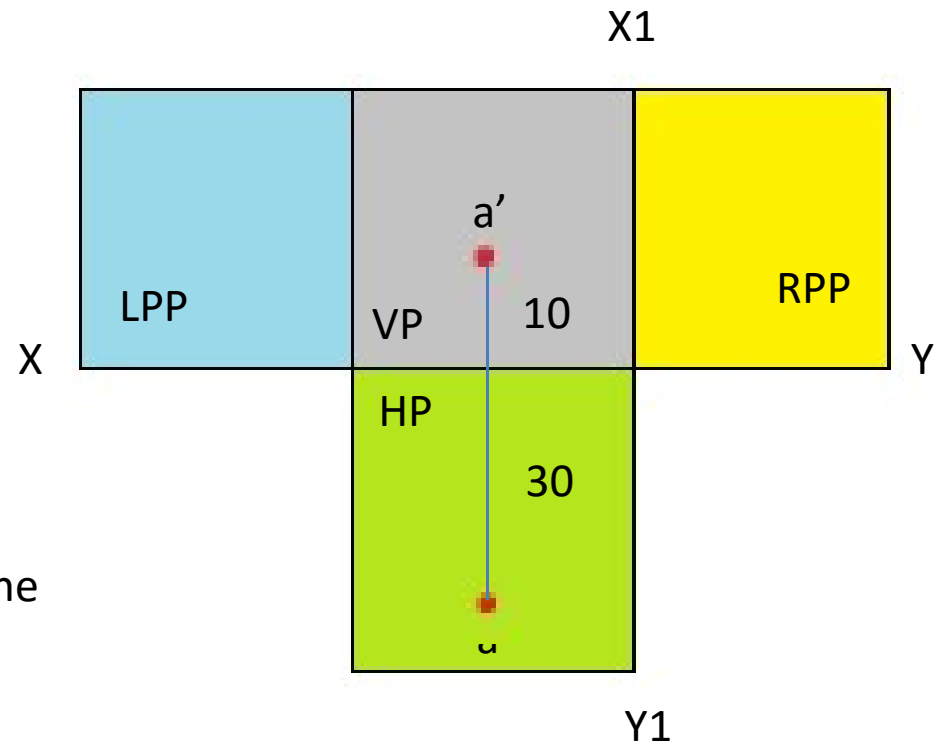
And to **differentiate between different views** they are represented as follows.

- **Top View (a)** – Only small letter (i.e. a, b)
- **Front View (a')** (– small letter with single dash (i.e. a', b')
- **Side View (a'')** – Small letter with double dash (i.e. a'', b'' ...)

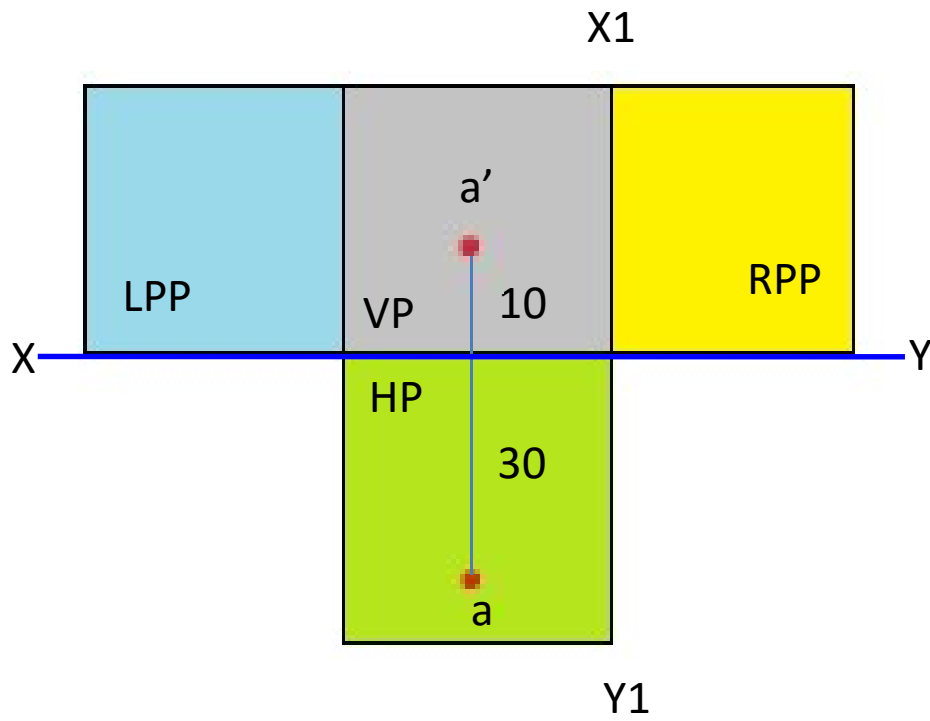
1 - Quadrant



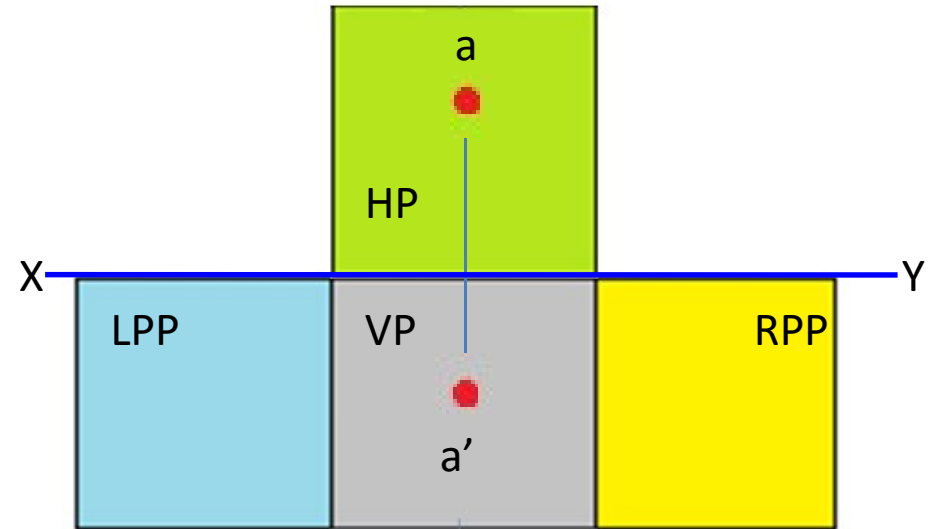
1 - Quadrant



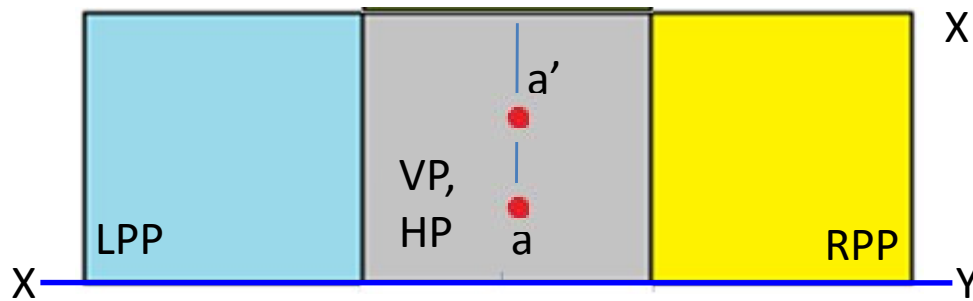
1 - Quadrant



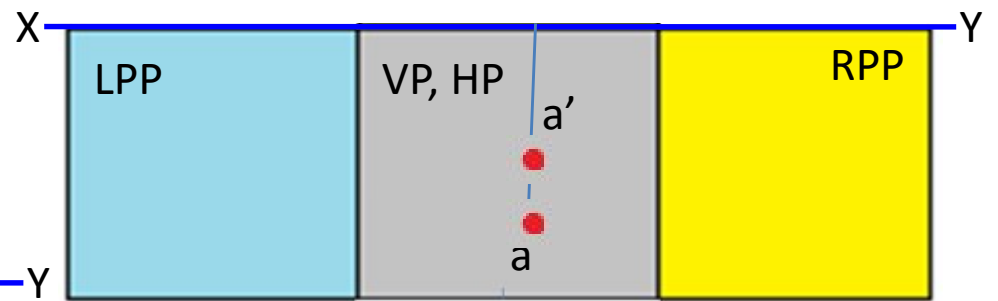
3- Quadrant



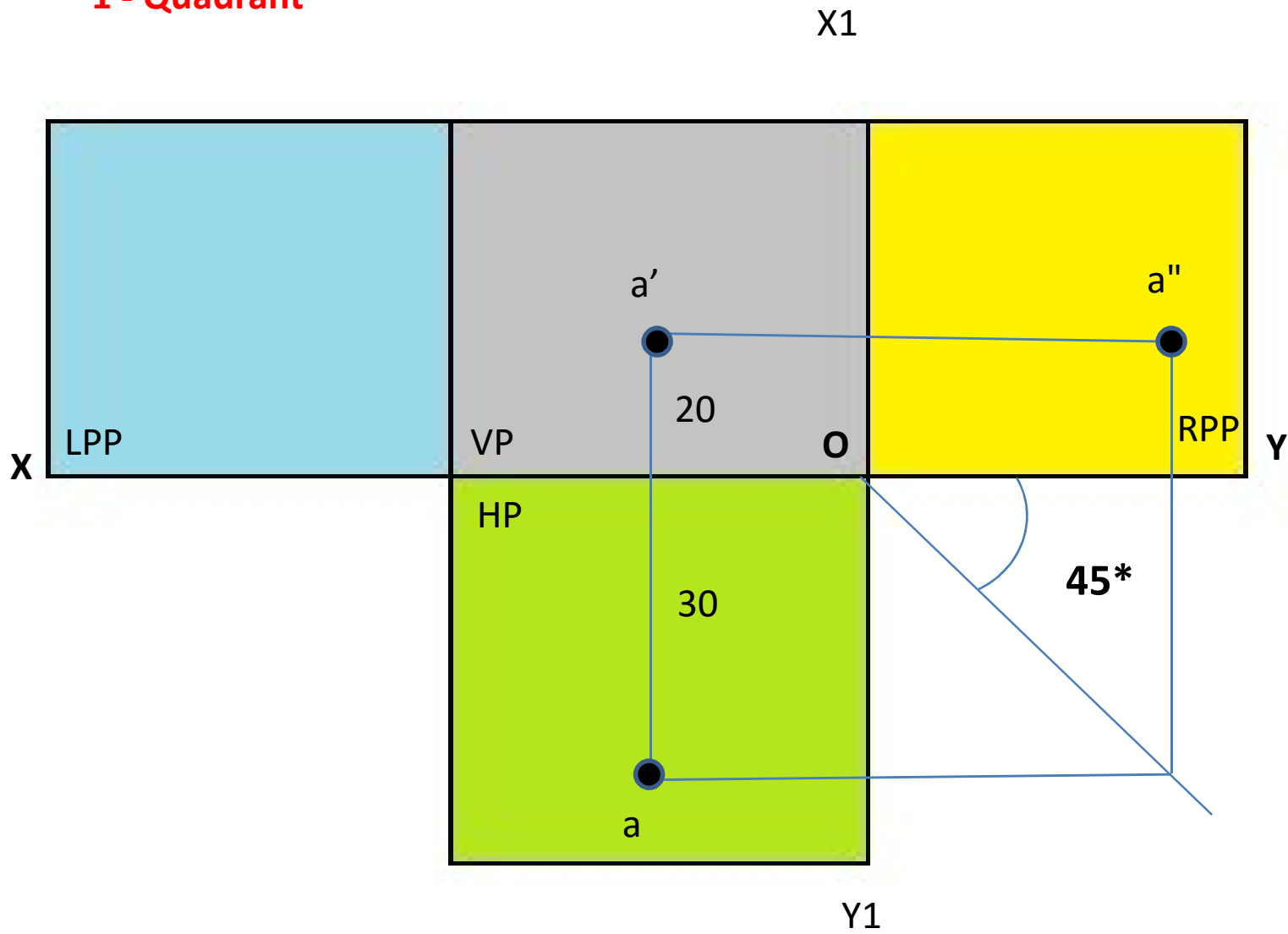
2 - Quadrant



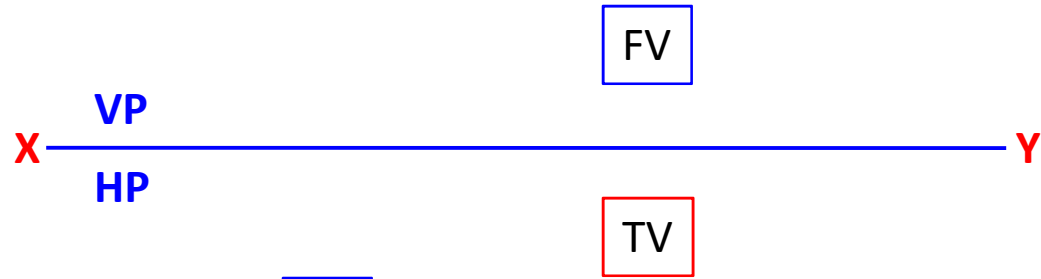
4 - Quadrant



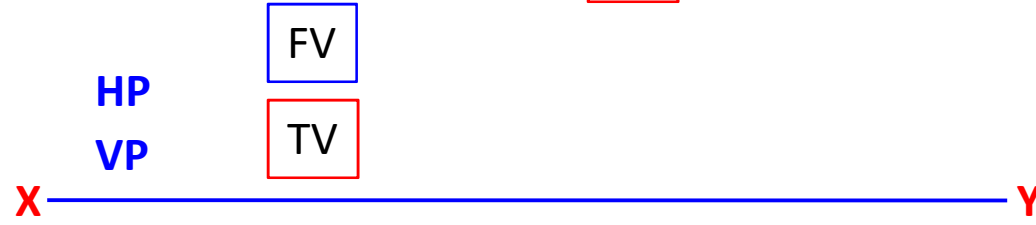
1 - Quadrant



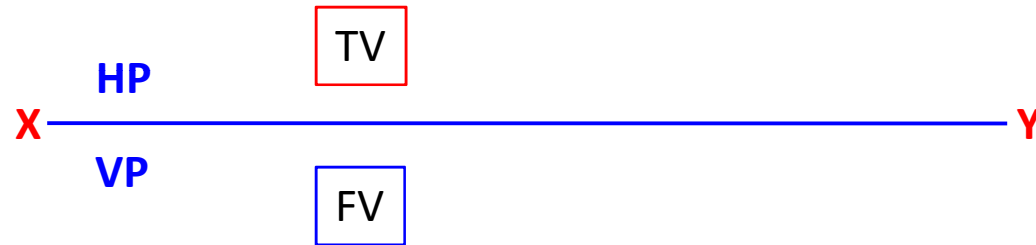
1- Q



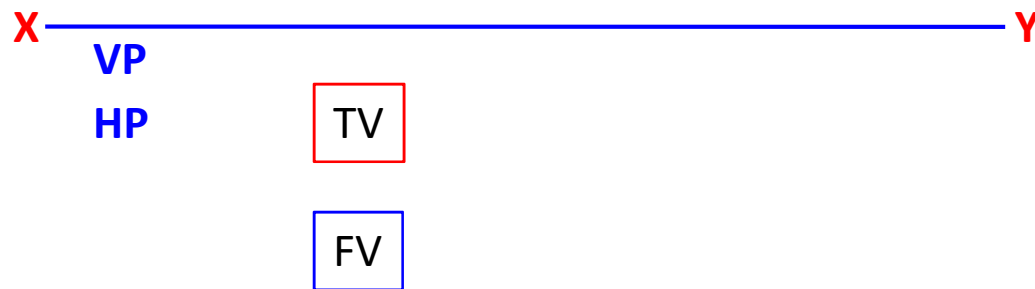
2- Q



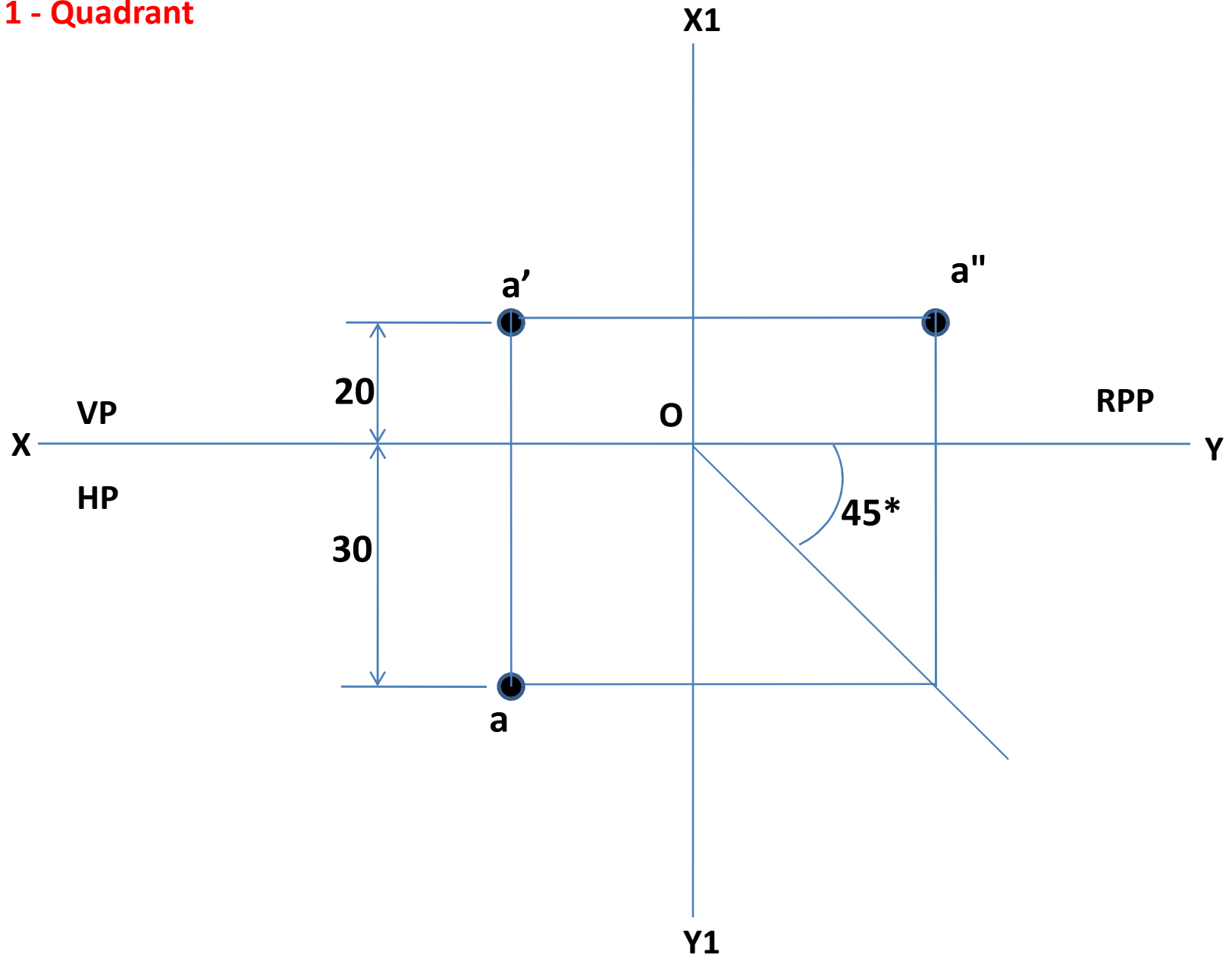
3- Q



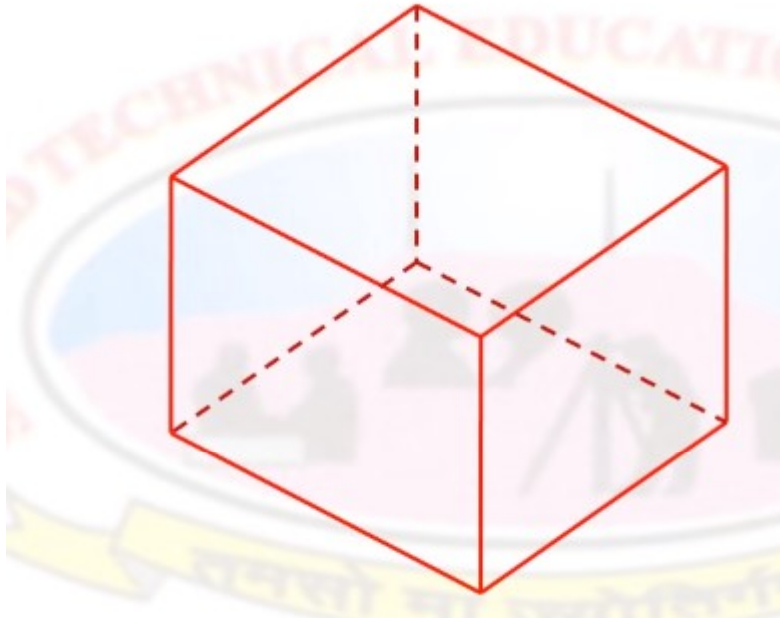
4- Q



1 - Quadrant



Glass box concept



Projections (Orthographic Projection) of Points (Object)

In Orthographic projection of Points (**Point** is considered as an **Object**) .

Point is a **dimensionless object** (It has no size) i.e. no width, no length and no depth. A point in geometry just shows the **location**.

A **point** is shown (denoted) by a **dark dot** (\bullet)

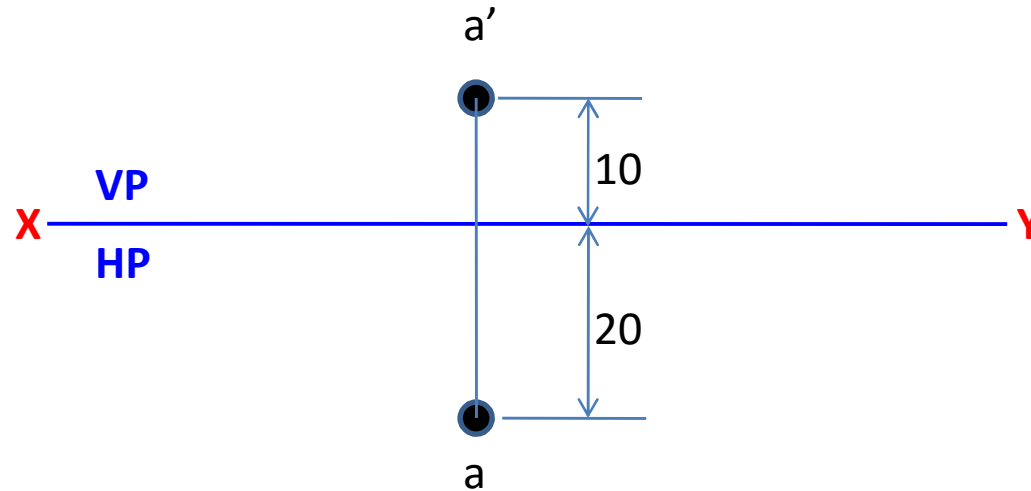
Orthographic projection of a Point is defined as obtaining the views of an Point (Object) on Different POP's using principles of orthographic projection.

PROBLEMS ON PROJECTION OF POINTS

Let us draw the projections of Point (Views of Points) considering it in a **Different Quadrants Or Different angles of Projection**.

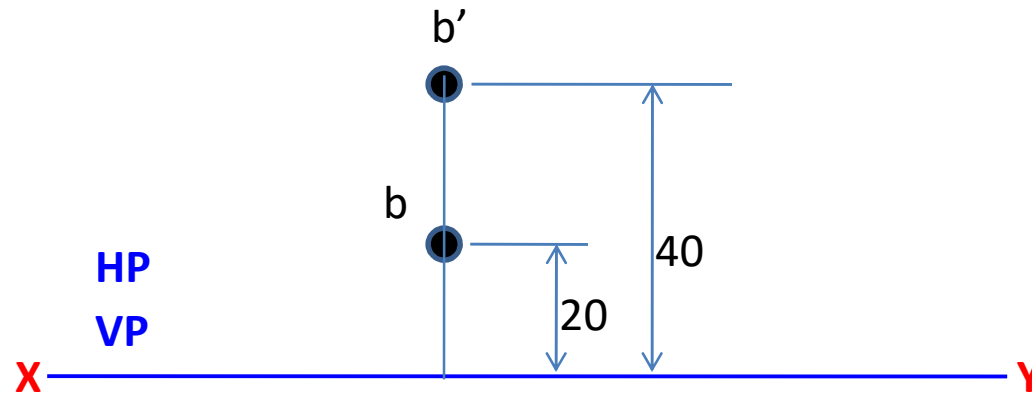
P1. Point A is 10 mm above HP and 20 mm in-front of VP, Draw the Projection of Point A.

1- Q



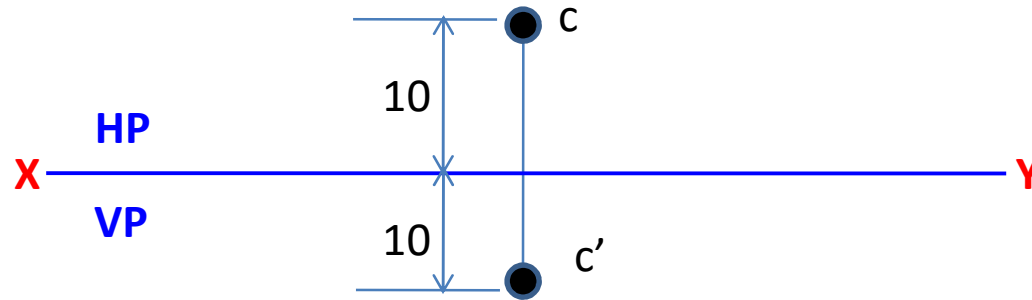
P2. Point B is 40 mm above HP and 20 mm behind VP, Draw its FV and TV.

2- Q



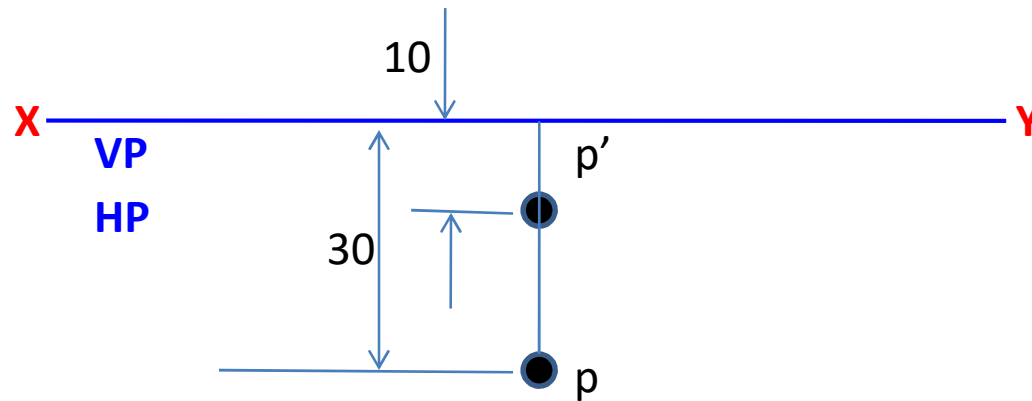
P3. Point C is 10 mm below HP and 10 mm behind VP, Draw the Projection of Point C.

3- Q



P4. Point P is 10 mm below HP and 30 mm in-front of VP, Draw FV & TV of Point P.

4- Q

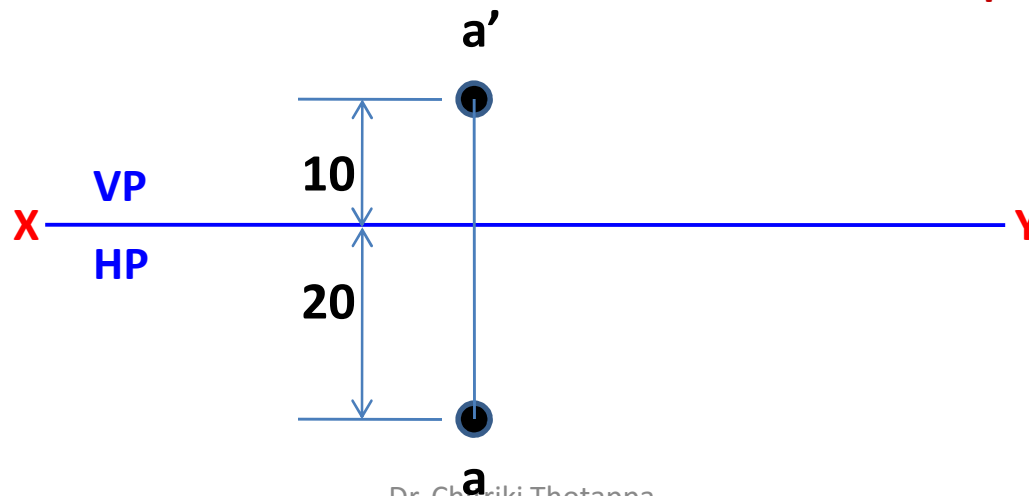


NOTE:

- XY line & X1Y1 lines should be **light** (2H pencil)
- Projection lines / Projectors should be **v v light** (2H Pencil)
- Point View should be **dark** (•) (HB Pencil)
- Naming of views a, a', a'' should be **dark** (HB Pencil)
- All naming and Dimension Nos. should be **dark** (HB Pencil)
- Dimension lines, Extension lines should be **light** (2H Pencil)
- Arrow head dark should be **dark** W:L 1: 3 (HB Pencil)

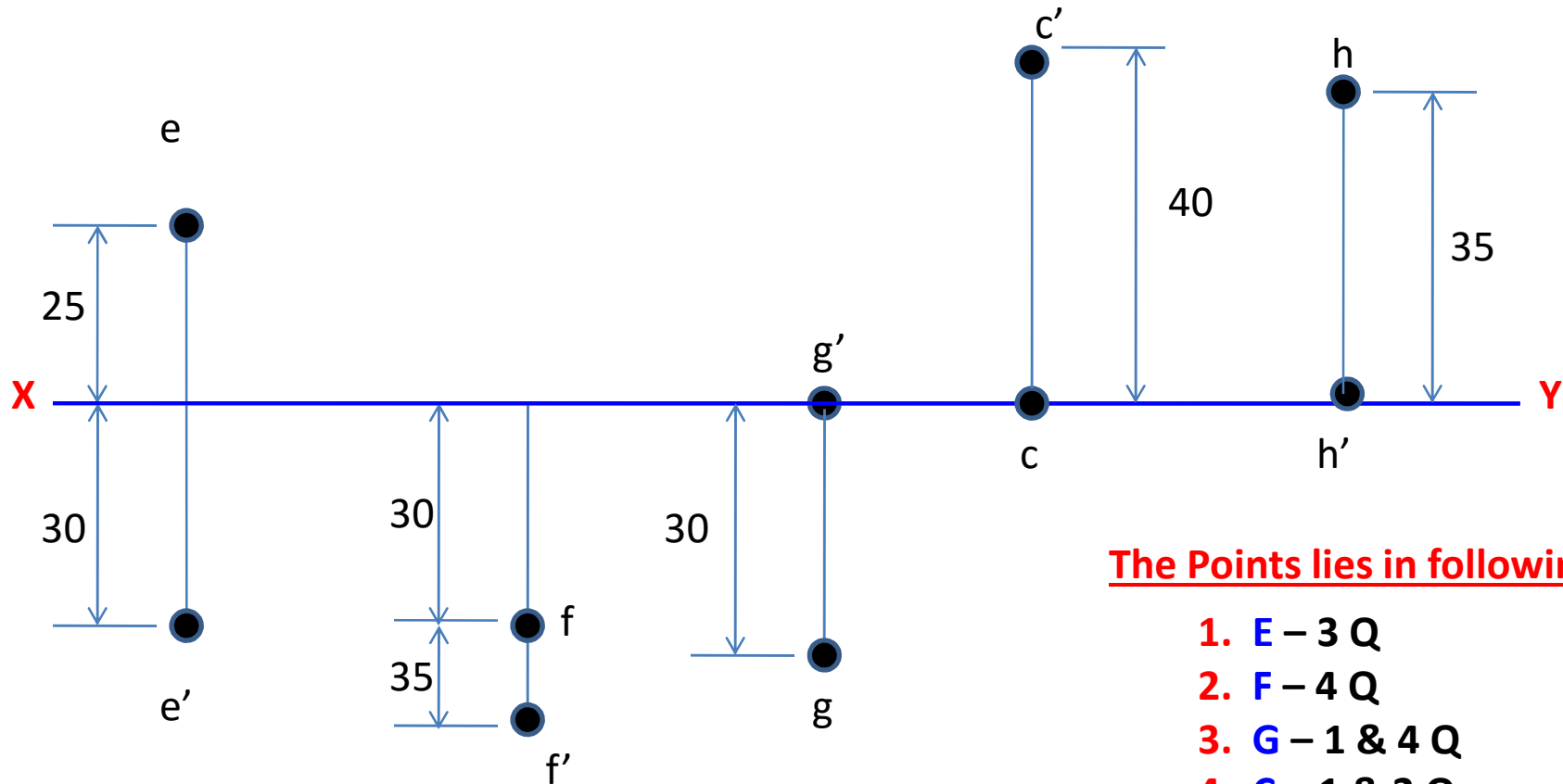
Q. Point A 10 mm above HP and 20 mm in-front of VP, Draw the projections.

1- Q



QBP2. Draw the Projections of the following Points on the same XY line, keeping convenient distance between each projectors . Name the Quadrants in which they lie.

1. **E** – 30mm below HP & 25 mm behind VP.
2. **F** – 35mm below HP & 30mm in-front of VP.
3. **G** – On HP & 30 mm in-front of VP.
4. **C** – On VP & 40mm above HP.
5. **H** – On HP & 35mm behind VP.

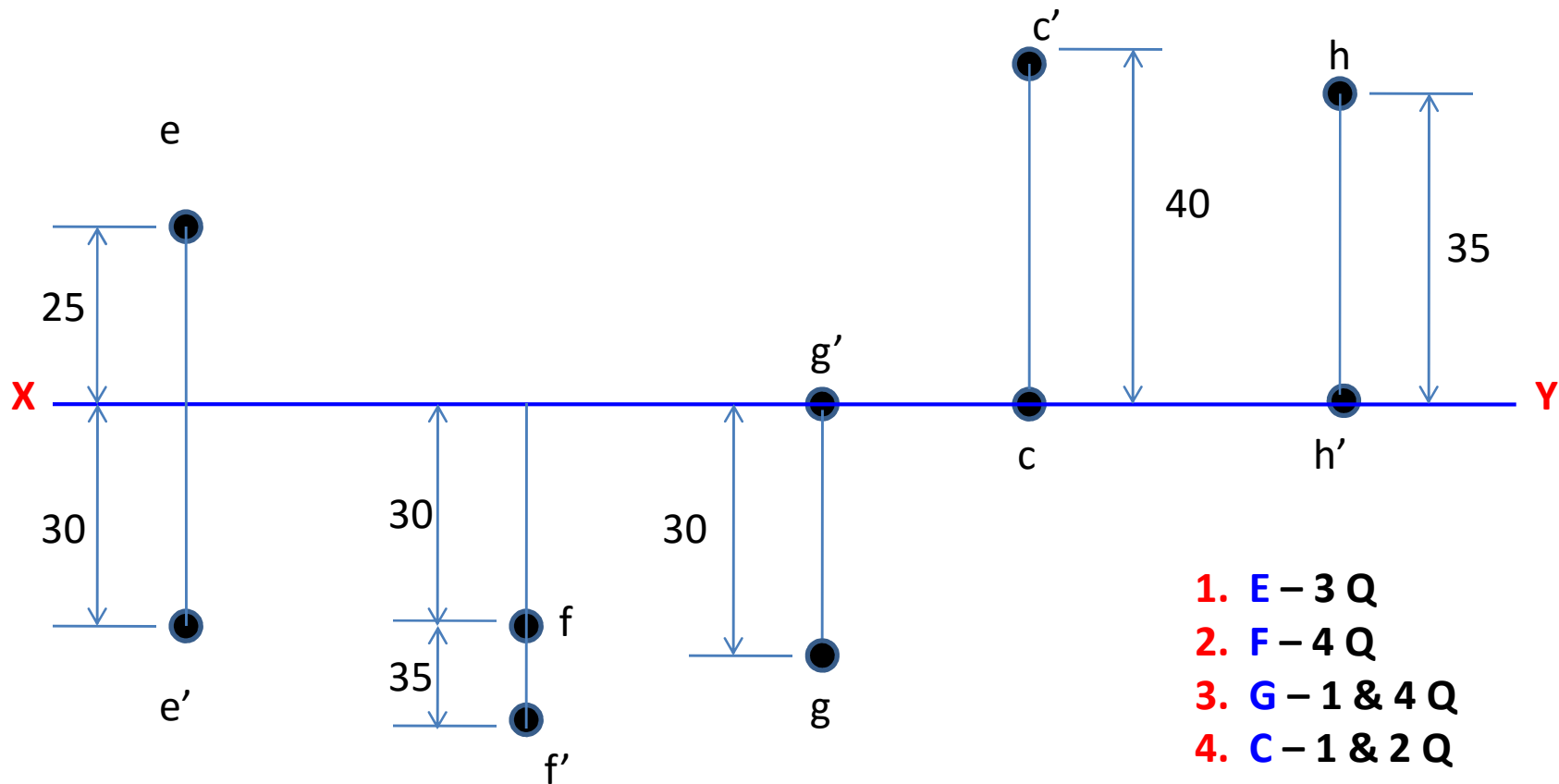


The Points lies in following Q

1. **E** – 3 Q
2. **F** – 4 Q
3. **G** – 1 & 4 Q
4. **C** – 1 & 2 Q
5. **H** – 2 & 3 Q

QBP2. Draw the Projections of the following Points on the same XY line, keeping convenient distance between each projectors . Name the Quadrants in which they lie.

1. **E** – 30mm below HP & 25 mm behind VP.
2. **F** – 35mm below HP & 30mm in-front of VP.
3. **G** – On HP & 30 mm in-front of VP.
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5. **H** – On HP & 35mm behind VP.



1. **E** – 3 Q
2. **F** – 4 Q
3. **G** – 1 & 4 Q
4. **C** – 1 & 2 Q
5. **H** – 2 & 3 Q

P10: A point **S** is in the **first quadrant** and **equidistant** of **50 mm** from all the three principal planes (i.e. HP, VP & RPP). Draw the projections of the point. Draw all the three views of the point.

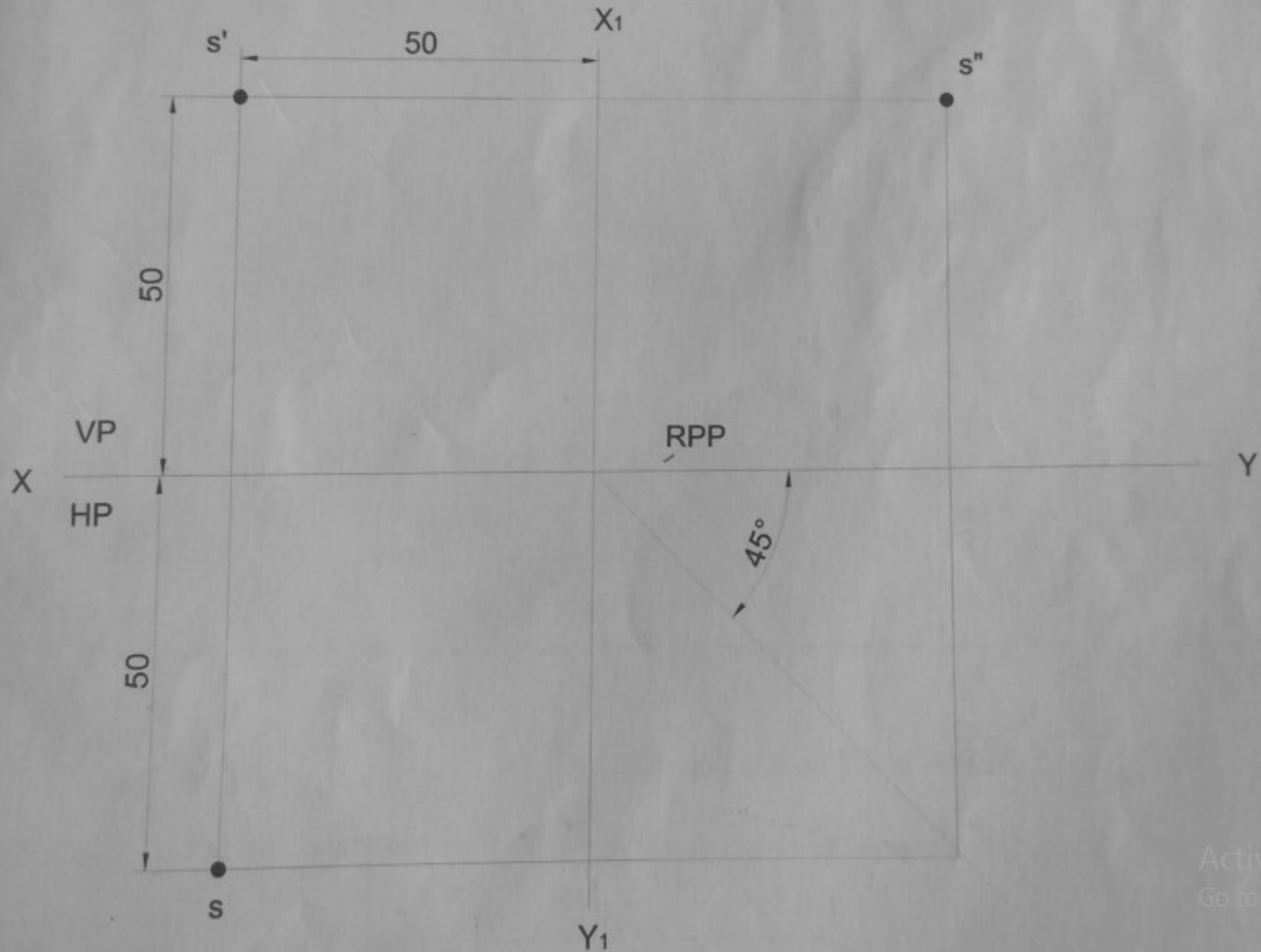
P10 Soln. Data given.

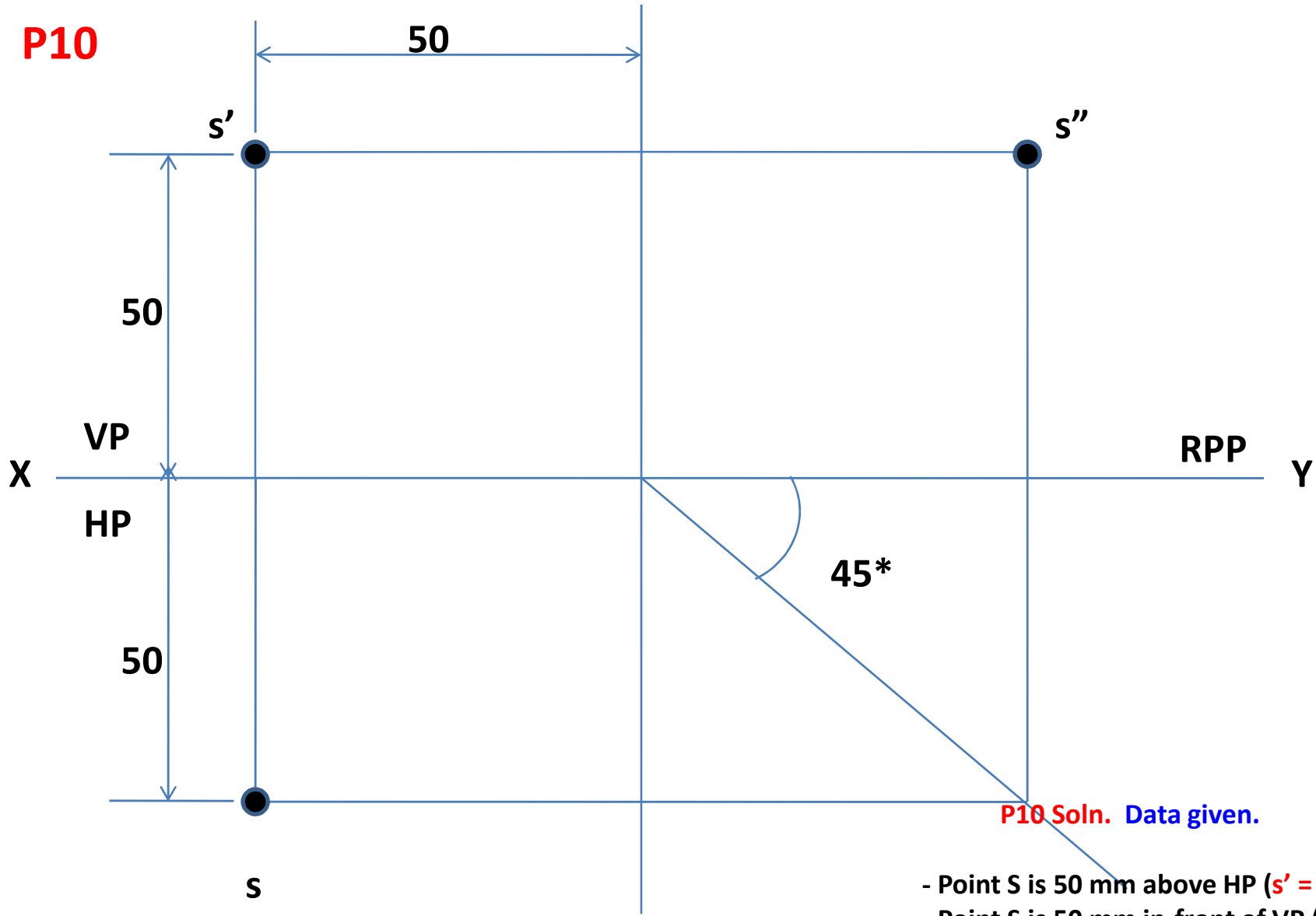
- Point S is 50 mm above HP ($s' = 50$)
- Point S is 50 mm in-front of VP ($s = 50$)
- Point S is 50 mm in-front of RPP

Draw: FV, TV & LPV in RPP

Problem 10 A point S is in the first quadrant and equidistant of 50 mm from all the three principal planes. Draw the projections of the point. Draw all the three views of the point.

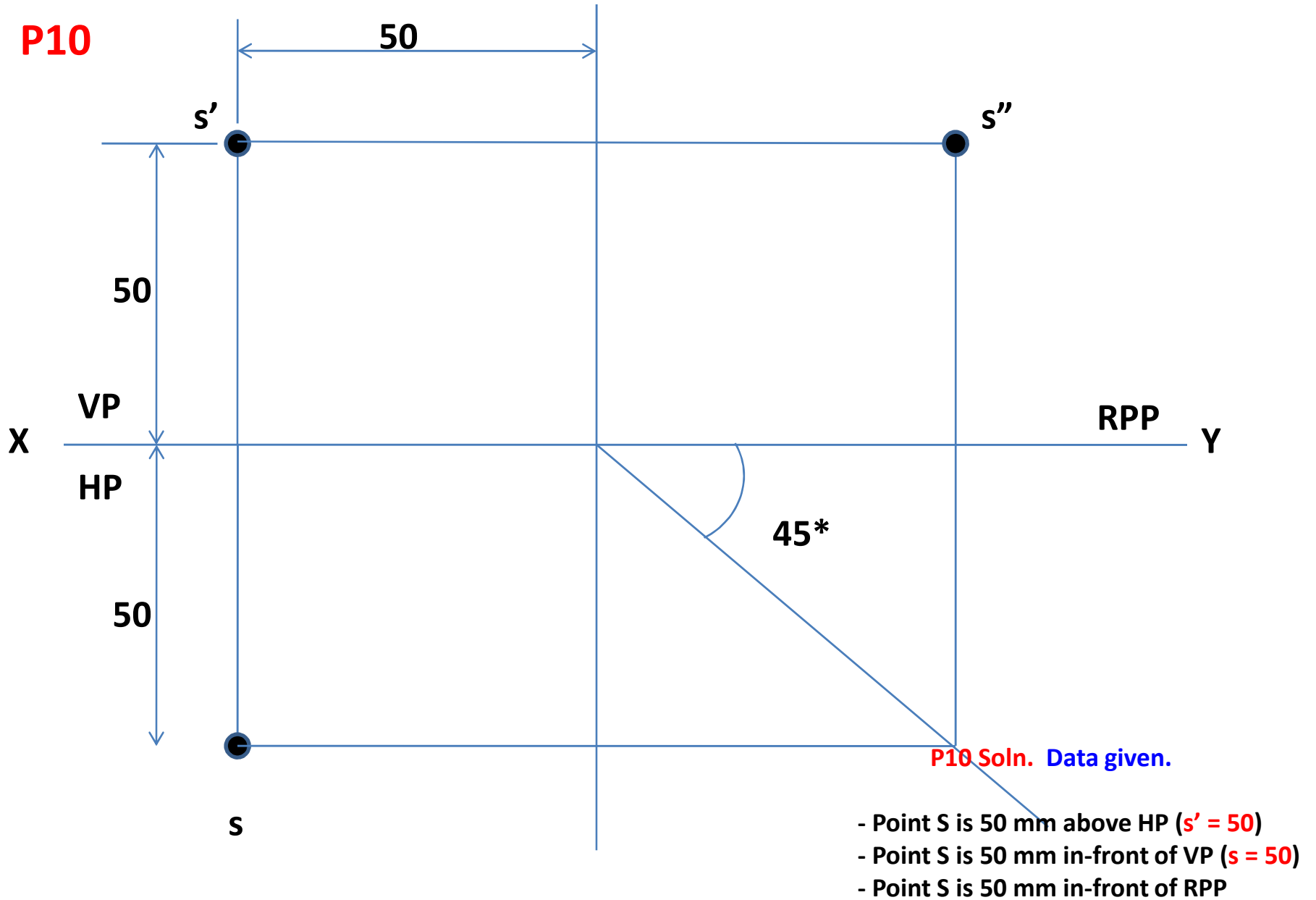
Solution





P10 Soln. Data given.

- Point S is 50 mm above HP ($s' = 50$)
- Point S is 50 mm in-front of VP ($s = 50$)
- Point S is 50 mm in-front of RPP

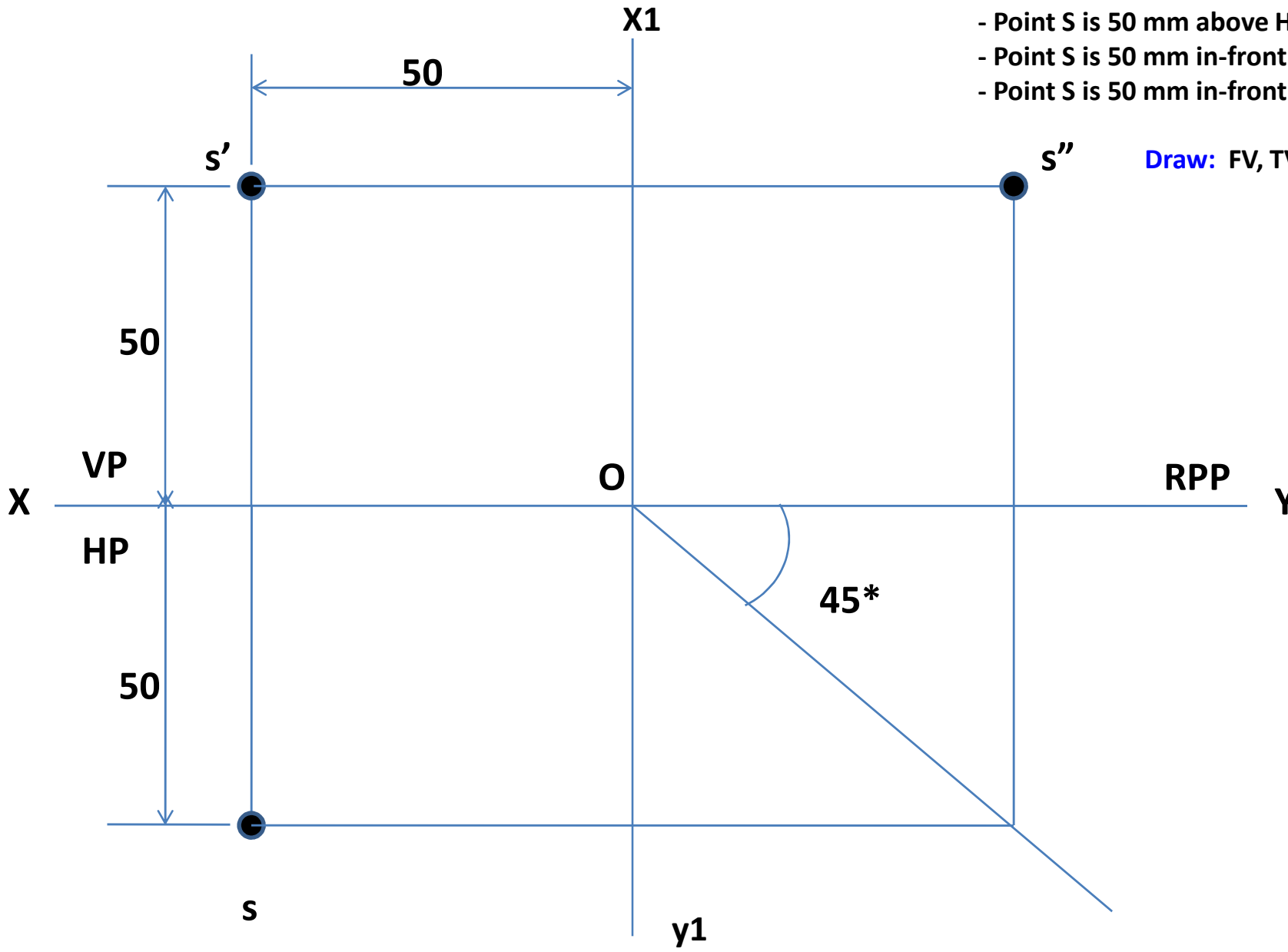


P10 Solution.

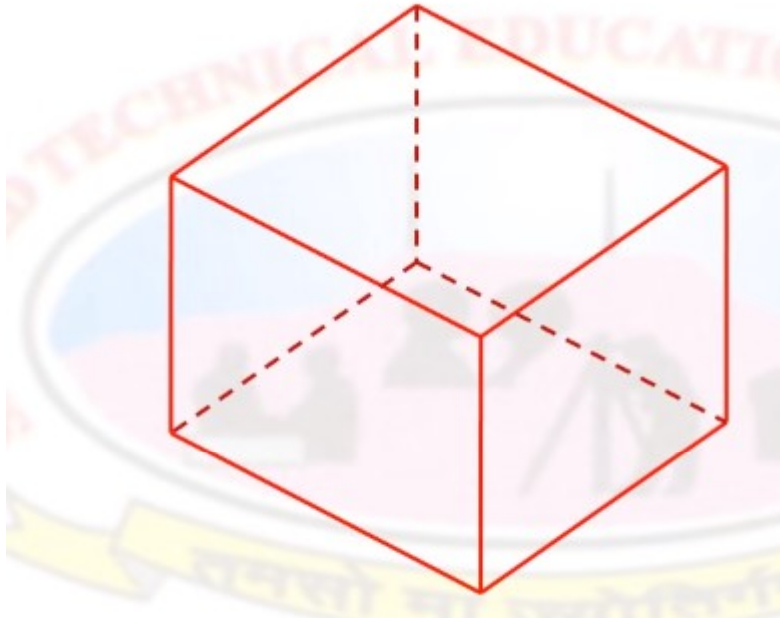
P10 Soln. Data given.

- Point S is 50 mm above HP ($s' = 50$)
- Point S is 50 mm in-front of VP ($s = 50$)
- Point S is 50 mm in-front of RPP

Draw: FV, TV & LPV in RPP



Glass box concept



P03: Draw and state the Quadrants in which the following points are located. Assume any distances.

- **A** – Front view is below XY line & Top view is above XY line.
- **B** – Front and Top Views are below XY line.
- **C** – Front and Top views are above XY line.
- **D** – Front view above XY line and Top View below XY line.

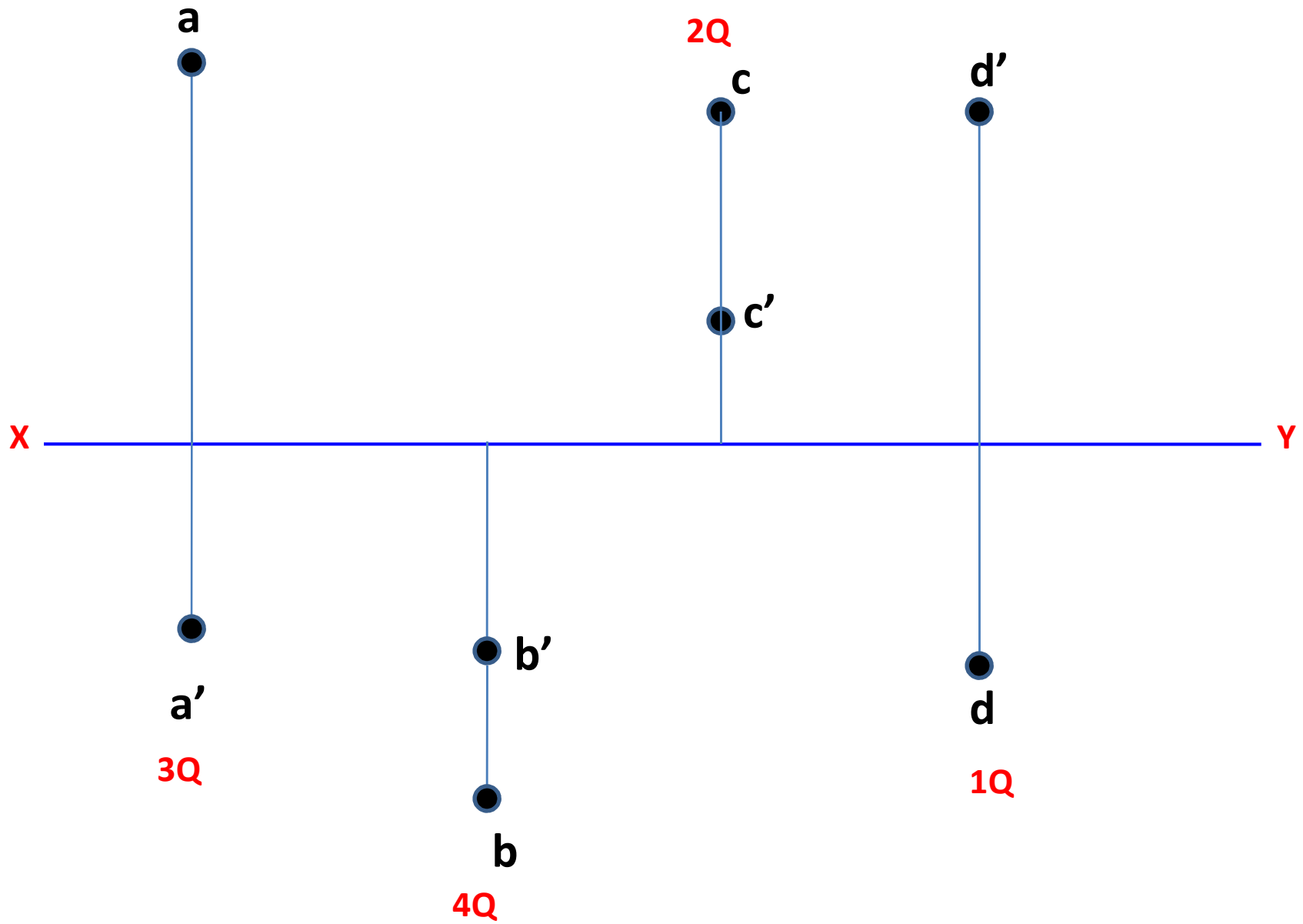
A - is below HP & behind VP

B – is Below HP & in-front of VP

C – is Above HP & behind VP

D – is Above HP & in-front of VP

P 03 : Soln.



END

